

Generalized factorization of PDEs:
A tool for finding their closed-form solutions,
dim ≥ 2

Sergey P. Tsarev

TU-Berlin, Germany

&

Krasnoyarsk SPU, Russia

email: `tsarev@math.tu-berlin.de`

`tsarev@newmail.ru`

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Outline

A teaser: $\dim = 2$, $\text{ord} = 2$, 1773

$\dim = 2$, $\text{ord} \geq 3$, 2005

refrain: Gröbner bases, Gröbner bases, ...

$\dim \geq 3$, $\text{ord} = 2$, 1901–2006

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Other interesting partial results

General theory of factorization of an arbitrary single LPDO

General approach: Abelian categories

Algorithmic problems

Acknowledgment

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$$\Leftrightarrow u = \frac{12(F(x) + G(y))}{(x+y)^2} - \frac{6(F'(x) + G'(y))}{x+y} + F''(x) + G''(y)$$

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In this case

$$u = c_0 F + c_1 F' + \dots + c_n F^{(n)} + d_0 G + d_1 G' + \dots + d_{n+1} G^{(n+1)}$$

with definite $c_i(x, y)$, $d_i(x, y)$ and $F(x)$, $G(y)$ — two arbitrary functions.

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How are solutions and factorizations of LPDEs related?

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$$\begin{cases} D_x u_1 = u_1 + 2u_2 + u_3, \\ D_y u_2 = -6u_1 + u_2 + 2u_3, \\ (D_x + D_y)u_3 = 12u_1 + 6u_2 + u_3. \end{cases}$$

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It has the complete explicit solution (S.Ts., ISSAC'2005):

$$\begin{cases} u_1 = 2e^y G(x) + e^x(3F(y) + F'(y)) + \exp \frac{x+y}{2} H(x-y), \\ u_2 = e^y G'(x) + 2e^x F'(y) - 2u_1, \\ u_3 = D_x u_1 + 3u_1 - 2(e^y G'(x) + 2e^x F'(y)), \end{cases}$$

where $F(y)$, $G(x)$ and $H(x-y)$ are three arbitrary functions of one variable each.

Technology (Ts., ISSAC'2005): generalized Laplace transformations

For this system the transformation is:

$$\begin{cases} \bar{u}_1 = u_1, \\ \bar{u}_2 = u_2 + 2u_1, \\ \bar{u}_3 = ((D_x + D_y)u_1 - u_1 - 2u_2 - 4u_1). \end{cases}$$

The transformed system:

$$\begin{cases} D_x \bar{u}_3 = \bar{u}_3, \\ D_y \bar{u}_2 = 2\bar{u}_3 + \bar{u}_2, \\ (D_x + D_y)u_1 = \bar{u}_3 + 2\bar{u}_2 + u_1. \end{cases}$$

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Alternative technology (F.Schwarz, 2005):

Transform the system into Janet (Gröbner) base, with term order: LEX, $u_3 > u_2 > u_1, x > y$:

$$u_{1,xy} - u_{1,xx} + u_{1,xyy} - 3u_{1,xy} + 2u_{1,x} - u_{1,yy} + 2u_{1,y} - u_1 = 0,$$

$$u_{2,y} + 3u_2 - 2u_{1,x} + 8u_1 = 0,$$

$$u_{2,x} - u_2 - \frac{1}{2}u_{1,xx} - \frac{1}{2}u_{1,xy} + 3u_{1,x} + \frac{1}{2}u_{1,y} - \frac{5}{2}u_1 = 0,$$

$$u_3 + 2u_2 - u_{1,x} + u_1 = 0.$$

The first equation *factors* (!!):

$$\begin{aligned} D_x^2 D_y - D_x^2 + D_x D_y^2 - 3D_x D_y + 2D_x - D_y^2 + 2D_y - 1 \\ = (D_x + D_y - 1)(D_y - 1)(D_x - 1). \end{aligned}$$

So one can find u_1 easily and then the other two functions u_2 and u_3 are obtained from the remaining equations of the Janet base.

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Conjecture: For *constant-coefficient* systems this Gröbner basis technology is equivalent to the generalized Laplace technology.

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U.Dini. *Sopra una classe di equazioni a derivate parziali di second'ordine con un numero qualunque di variabili*. Atti Acc. Lincei. Mem. Classe fis., mat., nat. (5) 4, 1901, p. 121–178.

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An example:

$$Lu = (D_x D_y + x D_x D_z - D_z)u = 0.$$

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$$Lu = (D_x D_y + x D_x D_z - D_z)u = 0.$$

It has a complete solution, obtained using Dini's procedures:

$$u = \int \left(v dx + (D_y + x D_z)v dz \right) + \theta(y),$$

where $v = \int \phi(x, xy - z) dx + \psi(y, z)$.

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How this solution was obtained?

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Dini transformation:

$$L = D_x D_y + x D_x D_z - D_z = (D_y + x D_z) D_x - D_z = D_x (D_y + x D_z) - 2 D_z.$$

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Now we can find v , and the u from (1).

$dim = 3, ord = 2$: general result

Theorem

Let $L = \sum_{i+j+k \leq 2} a_{ijk}(x, y, z) D_x^i D_y^j D_z^k$ have factorizable principal symbol: $\sum_{i+j+k=2} a_{ijk}(x, y, z) D_x^i D_y^j D_z^k = \hat{S}_1 \hat{S}_2$ (mod lower-order terms) with generic (non-commuting) first-order LPDO \hat{S}_1, \hat{S}_2 . Then there exist two Dini transformations $L_{(1)}, L_{(-1)}$ of L .

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Proof.

One can represent L in two possible ways:

$$L = \hat{S}_1 \hat{S}_2 + \hat{T} + a(x, y, z) = \hat{S}_2 \hat{S}_1 + \hat{U} + a(x, y, z)$$

with some first-order LPDO \hat{T}, \hat{U} . We will consider the first one obtaining a transformation of L into $L_{(1)}$.

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$$\text{Let } L = (\hat{S}_1 + \alpha)(\hat{S}_2 + \beta)$$

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When $[(\hat{S}_2 + \beta), (\hat{V} + b)]u$ can be transformed into an expression involving *only* v ?

Proof (cont.)

$$\text{Then } Lu = (\hat{S}_1 + \alpha) \underbrace{(\hat{S}_2 + \beta)u}_v + \hat{V}u + bu = 0 \iff$$

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One can check that this is possible to do choosing $\alpha(x, y, z)$ and $\beta(x, y, z)$ appropriately (for *generic* \hat{S}_i, \hat{V}).

$dim = 3, ord = 2$: chains of Dini transformations

$$\dots \leftarrow L_{(-2)} \leftarrow L_{(-1)} \leftarrow L \rightarrow L_{(1)} \rightarrow L_{(2)} \rightarrow \dots$$

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Other interesting partial results

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(the same even for multivariate polynomials!)

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- ▶ If a LPDO of order n is solvable then its symbol splits into n linear factors.

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Algebraically: $M \cdot P = N \cdot L$.

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Problem: chains are infinite....

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For a given (say, determined) system of L.P.D.E. take the subcategory \mathcal{S}_{n-2} of (overdetermined) systems with solution space parameterized by functions of at most $n - 2$ variables. Then in the factorcategory $\mathcal{S}/\mathcal{S}_{n-2}$ ascending chains are finite!

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- 2) Is there an algorithm to factorize in $K[D_y]$ for *skew differential fields* K , for example in $Q(x, y, D_x)[D_y]$??
- 3) Is there an algorithm to solve *a first-order* linear PDE with rational coefficients in $\dim = 3$ ($\dim = 2$ seems to be solved)?

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2) Anyone who will give comments :-)