

# Surfaces of section for geodesic flows of closed surfaces

Marco Mazzucchelli  
(CNRS and École normale supérieure de Lyon)

Joint work with:

- ▶ Gonzalo Contreras
- ▶ Gonzalo Contreras, Gerhard Knieper, Benjamin Schulz

# Surfaces of section

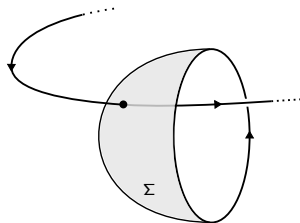
$N$  closed 3-manifold,  
 $X$  nowhere vanishing vector field,  
 $\phi_t : N \rightarrow N$  flow of  $X$

# Surfaces of section

$N$  closed 3-manifold,  
 $X$  nowhere vanishing vector field,  
 $\phi_t : N \rightarrow N$  flow of  $X$

A **surface of section** is a compact immersed surface  $\Sigma \looparrowright N$  such that:

- ▶  $\partial\Sigma$  is tangent to  $X$ ,
- ▶  $\text{int}(\Sigma)$  is embedded in  $N \setminus \partial\Sigma$  and transverse to  $X$ ,

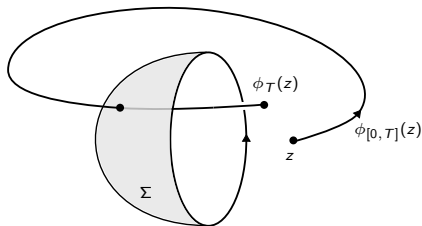


# Surfaces of section

$N$  closed 3-manifold,  
 $X$  nowhere vanishing vector field,  
 $\phi_t : N \rightarrow N$  flow of  $X$

A **global surface of section** is a compact immersed surface  $\Sigma \looparrowright N$  such that:

- ▶  $\partial\Sigma$  is tangent to  $X$ ,
- ▶  $\text{int}(\Sigma)$  is embedded in  $N \setminus \partial\Sigma$  and transverse to  $X$ ,
- ▶ for some  $T > 0$ , any orbit segment  $\phi_{[0,T]}(z)$  intersects  $\Sigma$ .



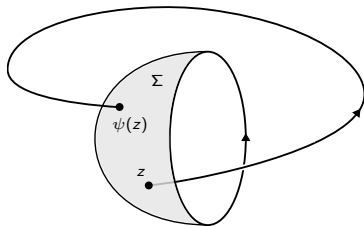
## Surfaces of section

$N$  closed 3-manifold,  
 $X$  nowhere vanishing vector field,  
 $\phi_t : N \rightarrow N$  flow of  $X$

A **global surface of section** is a compact immersed surface  $\Sigma \looparrowright N$  such that:

- ▶  $\partial\Sigma$  is tangent to  $X$ ,
- ▶  $\text{int}(\Sigma)$  is embedded in  $N \setminus \partial\Sigma$  and transverse to  $X$ ,
- ▶ for some  $T > 0$ , any orbit segment  $\phi_{[0,T]}(z)$  intersects  $\Sigma$ .

**First return map:**  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$



## Global surfaces of section – some history

- ▶ Notion was introduced by [Poincaré](#) in celestial mechanics

## Global surfaces of section – some history

- ▶ Notion was introduced by [Poincaré](#) in celestial mechanics
- ▶ ([Birkhoff](#), ~ 1917) Existence of global surfaces of sections for Riemannian geodesic flows of
  - Positively curved 2-spheres
  - Negatively curved closed surfaces

## Global surfaces of section – some history

- ▶ Notion was introduced by [Poincaré](#) in celestial mechanics
- ▶ ([Birkhoff](#), ~ 1917) Existence of global surfaces of sections for Riemannian geodesic flows of
  - Positively curved 2-spheres
  - Negatively curved closed surfaces
- ▶ ([Fried](#), 1981) Existence of global surfaces of sections for transitive Anosov flows



## Global surfaces of section – some history

- ▶ Notion was introduced by [Poincaré](#) in celestial mechanics
- ▶ ([Birkhoff, ~ 1917](#)) Existence of global surfaces of sections for Riemannian geodesic flows of
  - Positively curved 2-spheres
  - Negatively curved closed surfaces
- ▶ ([Fried, 1981](#)) Existence of global surfaces of sections for transitive Anosov flows
- ▶ ([Hofer-Wysocky-Zehnder, 1998](#)) Contact hypersurfaces  $N \subset \mathbb{C}^2$  admit a global surface of section  $\Sigma \cong B^2$  for their Reeb flow

## Global surfaces of section – some history

- ▶ Notion was introduced by [Poincaré](#) in celestial mechanics
- ▶ ([Birkhoff, ~ 1917](#)) Existence of global surfaces of sections for Riemannian geodesic flows of
  - Positively curved 2-spheres
  - Negatively curved closed surfaces
- ▶ ([Fried, 1981](#)) Existence of global surfaces of sections for transitive Anosov flows
- ▶ ([Hofer-Wysocky-Zehnder, 1998](#)) Contact hypersurfaces  $N \subset \mathbb{C}^2$  admit a global surface of section  $\Sigma \cong B^2$  for their Reeb flow
- ▶ ....

## Reeb flows and Geodesic flows

- ▶  $(N, \lambda)$  closed contact 3-manifold,  $X$  Reeb vector field

## Reeb flows and Geodesic flows

- ▶  $(N, \lambda)$  closed contact 3-manifold,  $X$  Reeb vector field

$\lambda$  1-form on  $N$

$\lambda \wedge d\lambda$  volume form

$\lambda(X) \equiv 1, \quad d\lambda(X, \cdot) \equiv 0$

## Reeb flows and Geodesic flows

- ▶  $(N, \lambda)$  closed contact 3-manifold,  $X$  Reeb vector field

$\lambda$  1-form on  $N$

$\lambda \wedge d\lambda$  volume form

$\lambda(X) \equiv 1, \quad d\lambda(X, \cdot) \equiv 0$

- ▶  $(M, g)$  closed Riemannian surface

## Reeb flows and Geodesic flows

- ▶  $(N, \lambda)$  closed contact 3-manifold,  $X$  Reeb vector field

$\lambda$  1-form on  $N$

$\lambda \wedge d\lambda$  volume form

$\lambda(X) \equiv 1, \quad d\lambda(X, \cdot) \equiv 0$

- ▶  $(M, g)$  closed Riemannian surface

$N = SM$  unit tangent bundle

$\lambda =$  Liouville contact form,

$X$  is the **geodesic vector field**

## Reeb flows and Geodesic flows

- ▶  $(N, \lambda)$  closed contact 3-manifold,  $X$  Reeb vector field

$\lambda$  1-form on  $N$

$\lambda \wedge d\lambda$  volume form

$\lambda(X) \equiv 1, \quad d\lambda(X, \cdot) \equiv 0$

- ▶  $(M, g)$  closed Riemannian surface

$N = SM$  unit tangent bundle

$\lambda =$  Liouville contact form,

$X$  is the **geodesic vector field**

$\phi_X^t(\dot{\gamma}(0)) = \dot{\gamma}(t)$ , where  $\gamma$  is a geodesic with  $\|\dot{\gamma}\|_g \equiv 1$

## Reeb flows

$X$  Reeb vector field of a closed 3-manifold  $(N, \lambda)$



## Reeb flows

$X$  Reeb vector field of a closed 3-manifold  $(N, \lambda)$

There always exists a closed orbit (Taubes 2007),  
indeed even two (Cristofaro G., Hutchings 2016)

# Reeb flows

$X$  Reeb vector field of a closed 3-manifold  $(N, \lambda)$

There always exists a closed orbit (Taubes 2007),  
indeed even two (Cristofaro G., Hutchings 2016)

**Theorem (Contreras, Mazzucchelli)** *If  $X$  satisfies the Kupka-Smale condition, then it has a global surface of section.*

# Reeb flows

$X$  Reeb vector field of a closed 3-manifold  $(N, \lambda)$

There always exists a closed orbit (Taubes 2007),  
indeed even two (Cristofaro G., Hutchings 2016)

**Theorem (Contreras, Mazzucchelli)** *If  $X$  satisfies the Kupka-Smale condition, then it has a global surface of section.*

**Theorem (Colin, Dehornoy, Hryniewicz, Rechtman)** *If  $X$  has equidistributed closed orbits, then it has a global surface of section.*

# Reeb flows

$X$  Reeb vector field of a closed 3-manifold  $(N, \lambda)$

There always exists a closed orbit (Taubes 2007), and indeed even two (Cristofaro G., Hutchings 2016)

**Theorem (Contreras, Mazzucchelli)** *If  $X$  satisfies the Kupka-Smale condition, then it has a global surface of section.*

**Theorem (Colin, Dehornoy, Hryniewicz, Rechtman)** *If  $X$  has equidistributed closed orbits, then it has a global surface of section.*

## Global surfaces of section of geodesic flows

$(M, g)$  closed orientable surface of genus  $G$

$\phi_t : SM \rightarrow SM$  geodesic flow

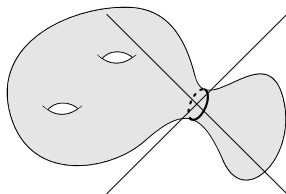
## Global surfaces of section of geodesic flows

$(M, g)$  closed orientable surface of genus  $G$

$\phi_t : SM \rightarrow SM$  geodesic flow

**Theorem (Contreras-Mazzucchelli-Knieper-Schulz)**

*If  $(M, g)$  has no contractible simple closed geodesics without conjugate points, there exists a global surface of section of genus one and  $8G - 4$  boundary components*



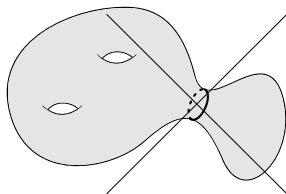
## Global surfaces of section of geodesic flows

$(M, g)$  closed orientable surface of genus  $G$

$\phi_t : SM \rightarrow SM$  geodesic flow

**Theorem (Contreras-Mazzucchelli-Knieper-Schulz)**

*If  $(M, g)$  has no contractible simple closed geodesics without conjugate points, there exists a global surface of section of genus one and  $8G - 4$  boundary components*



**Remark.** There are no contractible simple closed geodesics provided

$$\max K_g \leq \frac{2\pi}{\text{area}(M, g)}$$

# Global surfaces of section of geodesic flows

Theorem (Contreras-Knieper-Mazzucchelli-Schulz)

*If  $(M, g)$  has no contractible simple closed geodesics without conjugate points, there there exists a global surface of section of genus 1 and  $8G - 4$  boundary components*

Proof



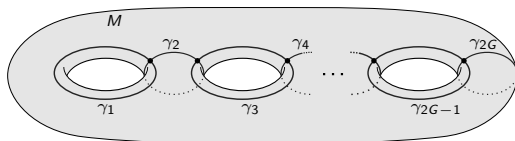
# Global surfaces of section of geodesic flows

Theorem (Contreras-Knieper-Mazzucchelli-Schulz)

*If  $(M, g)$  has no contractible simple closed geodesics without conjugate points, there there exists a global surface of section of genus 1 and  $8G - 4$  boundary components*

Proof

►  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$



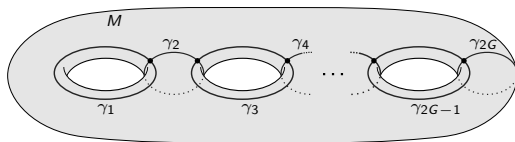
# Global surfaces of section of geodesic flows

Theorem (Contreras-Knieper-Mazzucchelli-Schulz)

*If  $(M, g)$  has no contractible simple closed geodesics without conjugate points, there there exists a global surface of section of genus 1 and  $8G - 4$  boundary components*

Proof

►  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$



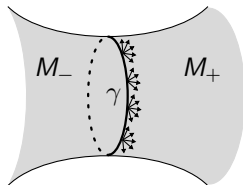
► No geodesic ray is trapped in  $M \setminus \Gamma$

(otherwise  $M \setminus \Gamma$  would contain a simple closed geodesic without conjugate points)

# Global surfaces of section of geodesic flows

- ▶ Birkhoff annuli of a simple closed geodesic  $\gamma$ :

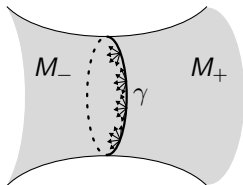
$$A_+(\gamma) := \{v \in SM|_\gamma \mid v \text{ points inside } M_+\}$$



## Global surfaces of section of geodesic flows

- ▶ Birkhoff annuli of a simple closed geodesic  $\gamma$ :

$$A_-(\gamma) := \{v \in SM|_\gamma \mid v \text{ points inside } M_-\}$$



# Global surfaces of section of geodesic flows

- ▶ Birkhoff annuli of a simple closed geodesic  $\gamma$ :

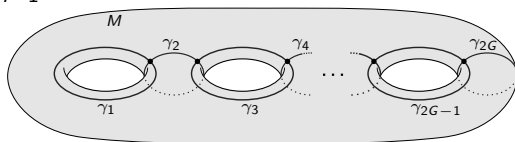
$$A_{\pm}(\gamma) := \{v \in SM|_{\gamma} \mid v \text{ points inside } M_{\pm}\}$$

# Global surfaces of section of geodesic flows

- ▶ Birkhoff annuli of a simple closed geodesic  $\gamma$ :

$$A_{\pm}(\gamma) := \{v \in SM|_{\gamma} \mid v \text{ points inside } M_{\pm}\}$$

- ▶  $\Sigma = \bigcup_{i=1}^{2G} A_{+}(\gamma_i) \cup A_{-}(\gamma_i)$

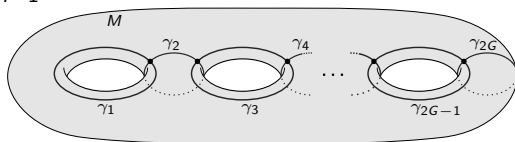


# Global surfaces of section of geodesic flows

- ▶ Birkhoff annuli of a simple closed geodesic  $\gamma$ :

$$A_{\pm}(\gamma) := \{v \in SM|_{\gamma} \mid v \text{ points inside } M_{\pm}\}$$

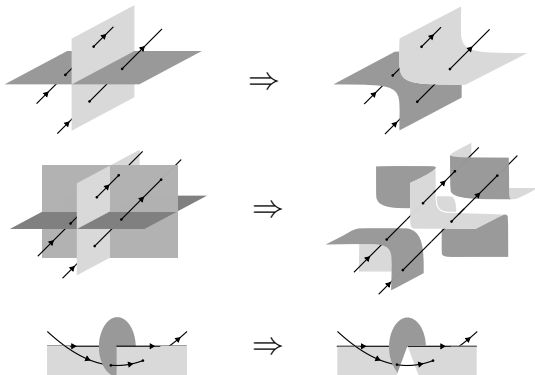
- ▶  $\Sigma = \bigcup_{i=1}^{2G} A_{+}(\gamma_i) \cup A_{-}(\gamma_i)$



$\Sigma$  is almost global surface of section, except that it has self-intersections.

# Global surfaces of section of geodesic flows

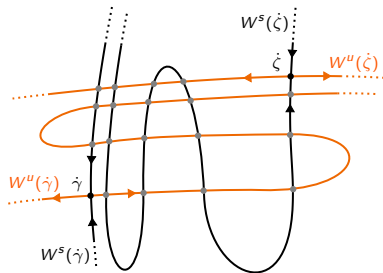
- ▶ (Fried) Resolve self-intersections of  $\Sigma$  with surgery:





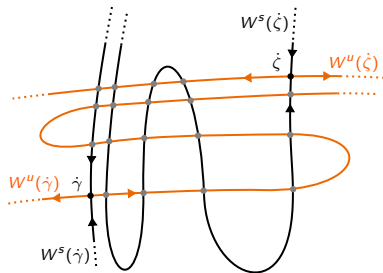
## A weak Kupka-Smale condition

We require all the contractible simple closed geodesics without conjugate points  $\gamma, \zeta$  to be **hyperbolic**, and  $W^s(\dot{\gamma}) \pitchfork W^u(\dot{\zeta})$ :



## A weak Kupka-Smale condition

We require all the contractible simple closed geodesics without conjugate points  $\gamma, \zeta$  to be **hyperbolic**, and  $W^s(\dot{\gamma}) \pitchfork W^u(\dot{\zeta})$ :



**Theorem (Contreras-Paternain)**

*Weak Kupka-Smale holds for a  $C^\infty$ -generic Riemannian metric.*

## Main theorem

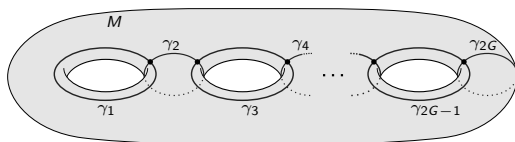
Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

# Main theorem

Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

Proof.

- ▶  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$  simple closed geodesics considered before



## Main theorem

Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

Proof.

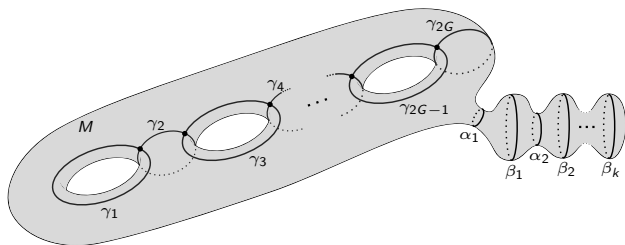
- ▶  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$  simple closed geodesics considered before
- ▶ Assume some geodesic ray is trapped in  $M \setminus \Gamma$

# Main theorem

Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

Proof.

- ▶  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$  simple closed geodesics considered before
- ▶ Assume some geodesic ray is trapped in  $M \setminus \Gamma$

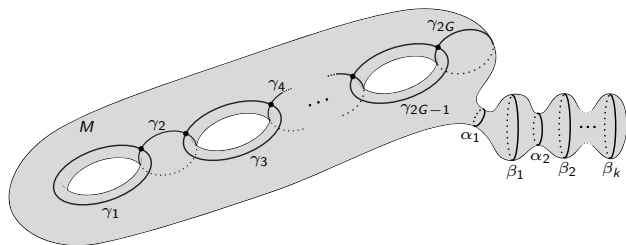


# Main theorem

Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

Proof.

- ▶  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$  simple closed geodesics considered before
- ▶ Assume some geodesic ray is trapped in  $M \setminus \Gamma$



$$A = \alpha_1 \cup \dots \cup \alpha_k, \quad B = \beta_1 \cup \dots \cup \beta_k$$

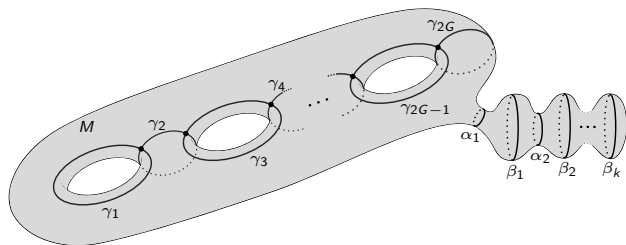
No complete geodesic is contained in  $M \setminus (\Gamma \cup A \cup B)$

# Main theorem

Theorem (Contreras-Knieper-Mazzucchelli-Schulz). *Any weak Kupka-Smale geodesic flow admits a global surface of section.*

Proof.

- ▶  $\Gamma = \gamma_1 \cup \dots \cup \gamma_{2G}$  simple closed geodesics considered before
- ▶ Assume some geodesic ray is trapped in  $M \setminus \Gamma$



$$A = \alpha_1 \cup \dots \cup \alpha_k, \quad B = \beta_1 \cup \dots \cup \beta_k$$

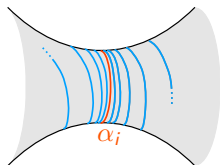
No complete geodesic is contained in  $M \setminus (\Gamma \cup A \cup B)$

Geodesic rays in  $M \setminus (\Gamma \cup A \cup B)$  are asymptotic to some  $\alpha_i$



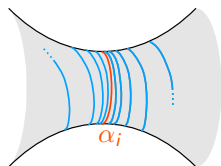
# Main theorem

- ▶ Some  $\alpha_j$  has homoclinics on both sides:

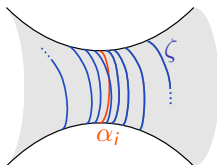


# Main theorem

- ▶ Some  $\alpha_j$  has homoclinics on both sides:

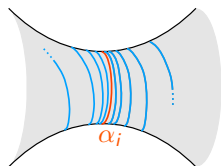


- ▶ The shadowing lemma provides a closed geodesic  $\zeta$  close to the homoclinics.

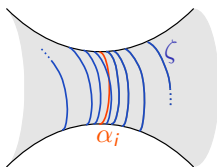


# Main theorem

- ▶ Some  $\alpha_j$  has homoclinics on both sides:



- ▶ The shadowing lemma provides a closed geodesic  $\zeta$  close to the homoclinics.



No geodesic ray in  $M \setminus (\Gamma \cup A \cup B \cup \zeta)$  is asymptotic to  $\alpha_j$ .

## Main theorem

- ▶ Repeat if needed for the other  $\alpha_j$ 's.

## Main theorem

- ▶ Repeat if needed for the other  $\alpha_j$ 's.
- ▶ We obtained a finite collection of closed geodesics  $Z$  such that  $M \setminus (\Gamma \cup A \cup B \cup Z)$  does not contain geodesic rays.

## Main theorem

- ▶ Repeat if needed for the other  $\alpha_j$ 's.
- ▶ We obtained a finite collection of closed geodesics  $Z$  such that  $M \setminus (\Gamma \cup A \cup B \cup Z)$  does not contain geodesic rays.
- ▶ Build a global surface of section by doing surgery on the Birkhoff annuli of  $\Gamma \cup A \cup B \cup Z$ .



## Application: characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow is Anosov.*

## Application: characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow is Anosov.*

**Corollary.** *On any closed surface, there exists an  $C^2$ -open dense subset  $\mathcal{U}$  of the space of Riemannian metrics such that any  $g \in \mathcal{U}$  is Anosov or has an elliptic closed geodesic.*



## Application: characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow is Anosov.*

**Corollary.** *On any closed surface, there exists an  $C^2$ -open dense subset  $\mathcal{U}$  of the space of Riemannian metrics such that any  $g \in \mathcal{U}$  is Anosov or has an elliptic closed geodesic.*

This corollary extends a theorem of [Contreras-Oliveira](#) for  $S^2$ , which extended a theorem of [Herman](#) for positively curved  $S^2$ , which in turn was first claimed (with a slightly wrong statement and an incomplete proof) by [Poincaré](#) in 1905.

## Application: characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow is Anosov.*

**Corollary.** *On any closed surface, there exists an  $C^2$ -open dense subset  $\mathcal{U}$  of the space of Riemannian metrics such that any  $g \in \mathcal{U}$  is Anosov or has an elliptic closed geodesic.*

**Corollary<sup>2</sup>.** *The geodesic flow of a closed Riemannian surface is  $C^2$ -structurally stable if and only if it is Anosov.*

Thank you for your attention!

## A characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold  $(N, \lambda)$  such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow  $\phi_t$  is Anosov.*

## A characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold  $(N, \lambda)$  such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow  $\phi_t$  is Anosov.*

Sketch of proof.

- ▶ (Taubes) There are infinitely many closed Reeb orbits.

## A characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold  $(N, \lambda)$  such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow  $\phi_t$  is Anosov.*

Sketch of proof.

- ▶ (Taubes) There are infinitely many closed Reeb orbits.
- ▶ Smale's spectral decomposition:

$$\overline{\text{Per}(X)} = \Lambda_1 \cup \dots \cup \Lambda_n,$$

where each  $\Lambda_i$  is a **basic set** (compact, locally maximal, invariant subset containing a dense orbit and a dense subset of periodic orbits).

## A characterization of Anosov Reeb flows

**Theorem (Contreras-Mazzucchelli).** *Let  $X$  be the Reeb vector field of a closed contact 3-manifold  $(N, \lambda)$  such that:*

- ▶  $\overline{\text{Per}(X)}$  is hyperbolic,
- ▶  $W^u(\gamma_1) \pitchfork W^s(\gamma_2)$  for all closed Reeb orbits  $\gamma_1, \gamma_2 \subset \text{Per}(X)$ .

*Then the Reeb flow  $\phi_t$  is Anosov.*

Sketch of proof.

- ▶ (Taubes) There are infinitely many closed Reeb orbits.
- ▶ Smale's spectral decomposition:

$$\overline{\text{Per}(X)} = \Lambda_1 \cup \dots \cup \Lambda_n,$$

where each  $\Lambda_i$  is a **basic set** (compact, locally maximal, invariant subset containing a dense orbit and a dense subset of periodic orbits).

- ▶ One such  $\Lambda = \Lambda_i$  contains infinitely many closed Reeb orbits.

## A characterization of Anosov Reeb flows

- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .



## A characterization of Anosov Reeb flows

- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .
- ▶  $\Lambda$  has measure zero (Bowen-Ruelle)

## A characterization of Anosov Reeb flows

- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .
- ▶  $\Lambda$  has measure zero (Bowen-Ruelle)
- ▶  $W^s(\Lambda) \cup W^u(\Lambda)$  has measure zero (Poincaré recurrence)

## A characterization of Anosov Reeb flows

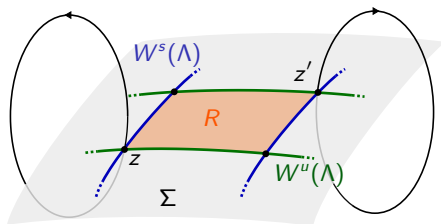
- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .
- ▶  $\Lambda$  has measure zero (Bowen-Ruelle)
- ▶  $W^s(\Lambda) \cup W^u(\Lambda)$  has measure zero (Poincaré recurrence)
- ▶  $W^s(\Lambda) \cap W^u(\Lambda) = \Lambda$

## A characterization of Anosov Reeb flows

- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .
- ▶  $\Lambda$  has measure zero (Bowen-Ruelle)
- ▶  $W^s(\Lambda) \cup W^u(\Lambda)$  has measure zero (Poincaré recurrence)
- ▶  $W^s(\Lambda) \cap W^u(\Lambda) = \Lambda$
- ▶ We consider a global surface of section  $\Sigma \subset N$ .  
Notice that  $\Lambda \cap \text{int}(\Sigma) \neq \emptyset$ .

# A characterization of Anosov Reeb flows

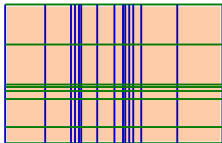
- ▶ We proceed by contradiction, assuming that the Reeb flow is not Anosov, and therefore  $\Lambda \subsetneq N$ .
- ▶  $\Lambda$  has measure zero (Bowen-Ruelle)
- ▶  $W^s(\Lambda) \cup W^u(\Lambda)$  has measure zero (Poincaré recurrence)
- ▶  $W^s(\Lambda) \cap W^u(\Lambda) = \Lambda$
- ▶ We consider a global surface of section  $\Sigma \subset N$ .  
Notice that  $\Lambda \cap \text{int}(\Sigma) \neq \emptyset$ .
- ▶ We fix a small heteroclinic rectangle  $R \subset \text{int}(\Sigma)$ :



$$z, z' \in \Lambda \cap \text{Per}(X)$$

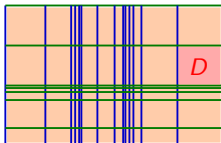
## A characterization of Anosov Reeb flows

- ▶  $R \cap (W^s(\Lambda) \cup W^u(\Lambda))$  is compact and connected



## A characterization of Anosov Reeb flows

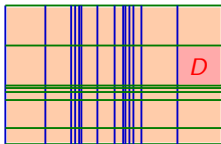
- ▶  $R \cap (W^s(\Lambda) \cup W^u(\Lambda))$  is compact and connected



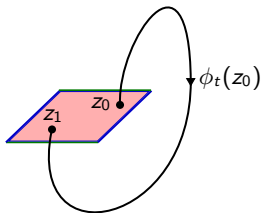
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component

# A characterization of Anosov Reeb flows

- ▶  $R \cap (W^s(\Lambda) \cup W^u(\Lambda))$  is compact and connected



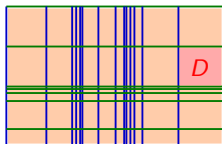
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component
- ▶ (Poincaré recurrence)  $\exists z_0 \in D$ ,  $t_0 > 0$  such that  $z_1 := \phi_{t_0}(z_0) \in D$ .



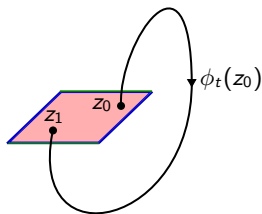


## A characterization of Anosov Reeb flows

- ▶  $R \cap (W^s(\Lambda) \cup W^u(\Lambda))$  is compact and connected



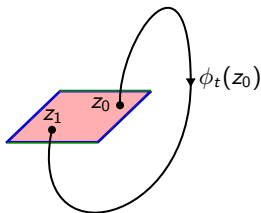
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component
- ▶ (Poincaré recurrence)  $\exists z_0 \in D$ ,  $t_0 > 0$  such that  $z_1 := \phi_{t_0}(z_0) \in D$ .



- ▶ We extend the map  $z_0 \mapsto z_1$  to a smooth return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$ .

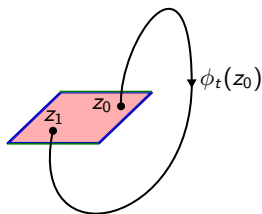
## A characterization of Anosov Reeb flows

- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component  
Return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$  extending  $z_0 \mapsto z_1$ .



## A characterization of Anosov Reeb flows

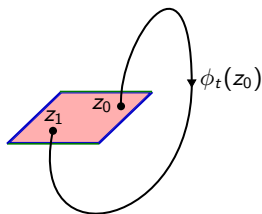
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component  
Return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$  extending  $z_0 \mapsto z_1$ .



- ▶ Since  $\partial D \subset (W^s(\Lambda) \cup W^u(\Lambda))$ ,  $D \cap (W^s(\Lambda) \cup W^u(\Lambda)) = \emptyset$ ,  
we must have  $\psi(D) \subset D$ .

## A characterization of Anosov Reeb flows

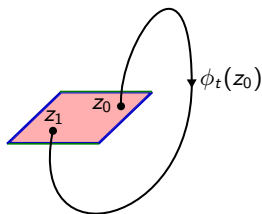
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component  
Return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$  extending  $z_0 \mapsto z_1$ .



- ▶ Since  $\partial D \subset (W^s(\Lambda) \cup W^u(\Lambda))$ ,  $D \cap (W^s(\Lambda) \cup W^u(\Lambda)) = \emptyset$ ,  
we must have  $\psi(D) \subset D$ .
- ▶  $\psi|_D : D \rightarrow D$  preserves the area form  $d\lambda|_D$ .

## A characterization of Anosov Reeb flows

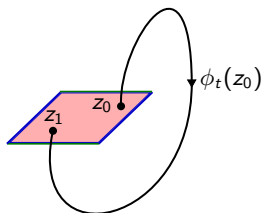
- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component  
Return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$  extending  $z_0 \mapsto z_1$ .



- ▶ Since  $\partial D \subset (W^s(\Lambda) \cup W^u(\Lambda))$ ,  $D \cap (W^s(\Lambda) \cup W^u(\Lambda)) = \emptyset$ ,  
we must have  $\psi(D) \subset D$ .
- ▶  $\psi|_D : D \rightarrow D$  preserves the area form  $d\lambda|_D$ .
- ▶ (Brower translation theorem)  $\psi$  has a fixed point  $z$ .

## A characterization of Anosov Reeb flows

- ▶  $D \subset R \setminus (W^s(\Lambda) \cup W^u(\Lambda))$  connected component  
Return map  $\psi : \text{int}(\Sigma) \rightarrow \text{int}(\Sigma)$  extending  $z_0 \mapsto z_1$ .



- ▶ Since  $\partial D \subset (W^s(\Lambda) \cup W^u(\Lambda))$ ,  $D \cap (W^s(\Lambda) \cup W^u(\Lambda)) = \emptyset$ , we must have  $\psi(D) \subset D$ .
- ▶  $\psi|_D : D \rightarrow D$  preserves the area form  $d\lambda|_D$ .
- ▶ (Brower translation theorem)  $\psi$  has a fixed point  $z$ .
- ▶ Thus  $z \in D \cap \text{Per}(X)$ . But  $D \cap \text{Per}(X) \subset D \cap \Lambda = \emptyset$ . □