

# Microlocal analysis of seven-dimensional Radon transforms for Compton scattering tomography

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- ▶ Motivated by Compton Scattering Tomography (CST), we present a microlocal analysis of two novel Radon transforms which map functions to their integrals over apple and lemon surfaces.

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  - ▶ To predict and analyze the image artifacts with incomplete data.
  - ▶ To mitigate artifacts when possible.

# The Compton Effect

*The Compton effect determines scattering angle*

$E_{\text{src}}$ =energy of *monochromatic* photons at the source,

$E_d$ =measured energy of scattered photon at detector,

$E_0$ =electron rest energy,  $\omega$ =scattering angle.

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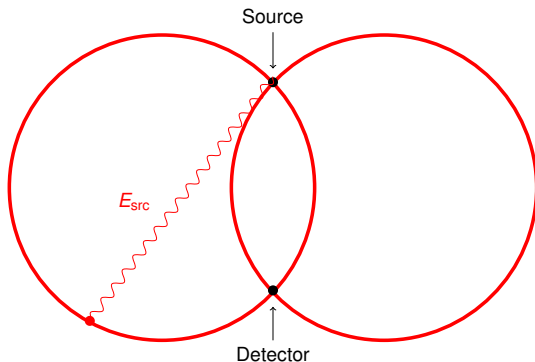
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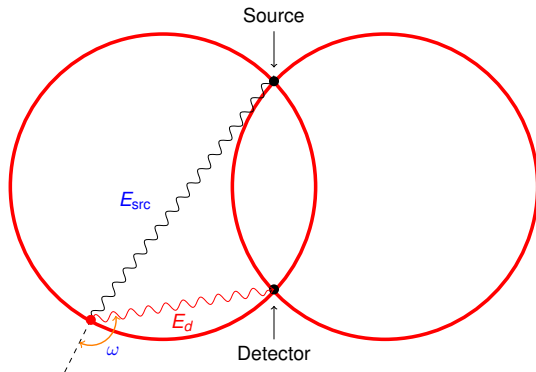
- ▶ *If two photons from the same source hit the detector with the same energy, they have the same scattering angle.*
- ▶ *Therefore, they are on the same circle containing the source and detector! (if on the same side)*

# Back scattered Compton Data are over *apples*



Photons leave the source with energy  $E_{\text{src}}$ .

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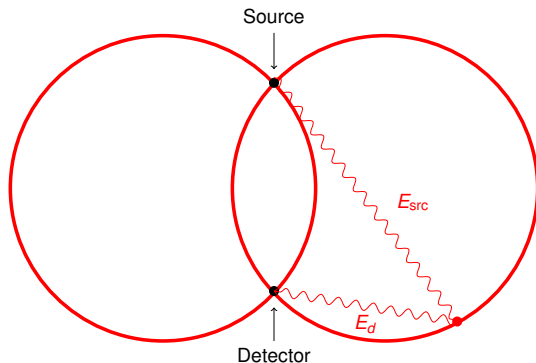


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Some will backscatter off the point with energy  $E_d$  measured at the detector.

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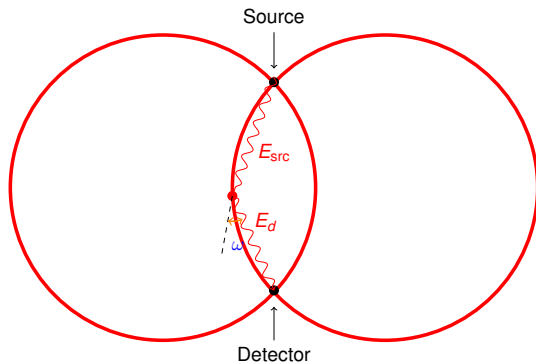
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The same scattering occurs on the other circle.

# Forward scattered Compton Data are over *lemons*



Photons leave the source with energy  $E_{src}$ .

Forward Scatter will occur on the lemon ( ) part between the source and detector with scattering angle  $\omega \in (0, \pi/2)$ .

# Previous works and dimensionality

1. Much of the literature considers these transforms over 3-D sets of lemons and apples [Webber, Q., Miller, Rigaud, Hahn, Webber, Holman, Cabeiro, et al.], [Arridge], etc.
2. [Rigaud, Hahn] With - 3-D data, artifacts observed due to incomplete data.
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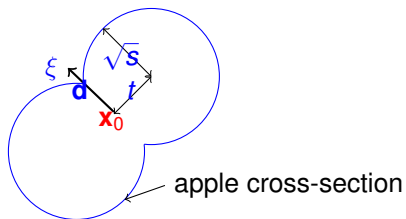
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*Common theme:* these authors analyze artifacts for various three-dimensional data sets.

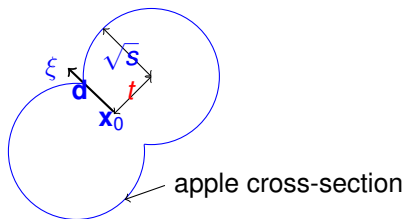


# The parametrization



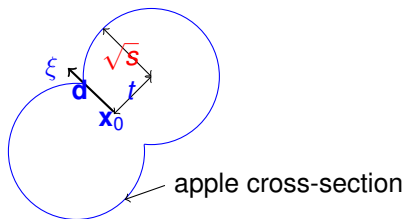
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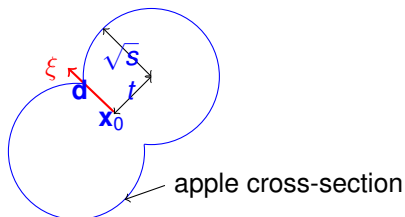
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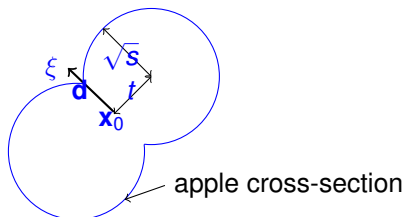
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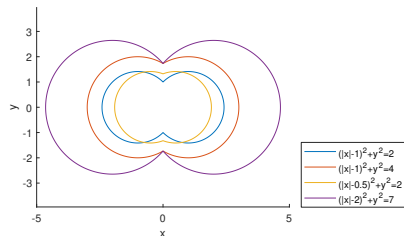
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$$\Psi_j(s, t, \mathbf{x}_0, \boldsymbol{\xi}; \mathbf{x}) = (\|\mathbf{x}_T - \langle \mathbf{x}_T, \boldsymbol{\xi} \rangle \boldsymbol{\xi}\| + (-1)^j t)^2 + \langle \mathbf{x}_T, \boldsymbol{\xi} \rangle^2 - s.$$

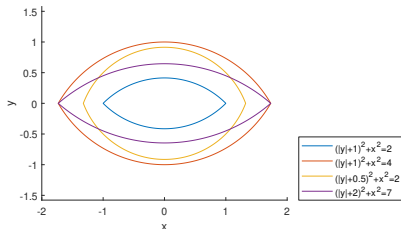
$\Psi_j = 0$  is the defining equation of the apple ( $j = 1$ ) and lemon ( $j = 2$ ) surfaces.

# Some example surfaces

Here are some 2-D cross-sections of apples and lemons with the defining equations highlighted.



Apples ( $j = 1$ )



Lemons ( $j = 2$ )

$(x, y)$  plane cross-sections of the apple and lemon parts of a spindle torus when  $\xi = (0, 1)$  (left) and  $\xi = (1, 0)$  (right),  $\mathbf{x}_0 = \mathbf{0}$ , and  $s$  and  $t$  vary between  $\frac{1}{2}$  and  $7$ .

# Our generalized Radon transform

$f \in L_c^2(B)$ , integrate over apple ( $j = 1$ ) and lemon ( $j = 2$ ) surfaces:

$$\mathcal{R}_j f(\mathbf{s}, t, \mathbf{x}_0, \xi) = \int_X \|\nabla_{\mathbf{x}} \Psi_j\| \delta(\Psi_j(\mathbf{s}, t, \mathbf{x}_0, \xi; \mathbf{x})) f(\mathbf{x}) d\mathbf{x}$$

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Let  $\bar{B}$  be the closed unit ball. The domain of  $\mathcal{R}_j f$  is defined

$$\begin{aligned}Y &= \{(\mathbf{s}, t, \mathbf{x}_0, \xi) \in \mathbb{R}^2 \times \mathbb{R}^3 \times \mathcal{S}^2 \\ &\quad : s > t^2, \{\mathbf{x}_0 \pm \sqrt{s - t^2} \xi\} \cap \bar{B} = \emptyset\},\end{aligned}$$

$Y$  describes the set of apples and lemons who's singular points (source and receiver) do not intersect  $\bar{B}$ .

# Main theorem

Theorem (Webber, Q. *Inverse Problems* **38**(2022))

*The apple and lemon transforms  $R_j : L_c^2(B) \rightarrow L_{loc}^2(Y)$  are elliptic FIO order  $-2$ .*

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- ▶ Also, we show there are no invisible singularities on  $B$  with data over all  $Y$ .

## Proof outline:

1. Calculate the canonical relation,  $\mathcal{C}_j$  of  $R_j$  and choose good coordinates.

$$R = R(\alpha, \beta) = \begin{pmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \beta & -\sin \beta \\ 0 & \sin \beta & \cos \beta \end{pmatrix}, \quad \xi = R\mathbf{e}_3.$$



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Each of these calculations has an expression:

$$\det \left( I_{3 \times 3} - \frac{t}{g} (r_1^T, r_2^T) \begin{pmatrix} r_1 \\ r_2 \end{pmatrix} \right) = \det \left( I_{2 \times 2} - \frac{t}{g} \begin{pmatrix} r_1 \\ r_2 \end{pmatrix} (r_1^T, r_2^T) \right)$$

where  $r_1$  and  $r_2$  are the first two rows of  $R^T$ ,  $g = \|\mathbf{x}_T - \langle \mathbf{x}_T, \xi \rangle \xi\|$ .

# A five-dimensional set of spindle tori

Corollary ([Webber, Q.])

Let  $\xi_0 \in S^2$  be fixed. Then the Radon transform over lemons with axis parallel  $\xi_0$

$$\mathcal{L}_T f(\mathbf{s}, t, \mathbf{x}_0) = \mathcal{L}f(\mathbf{s}, t, \mathbf{x}_0, \xi_0)$$

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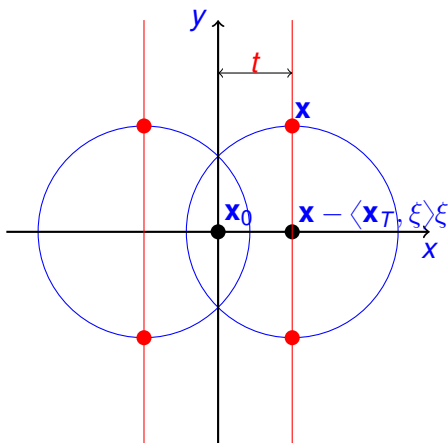
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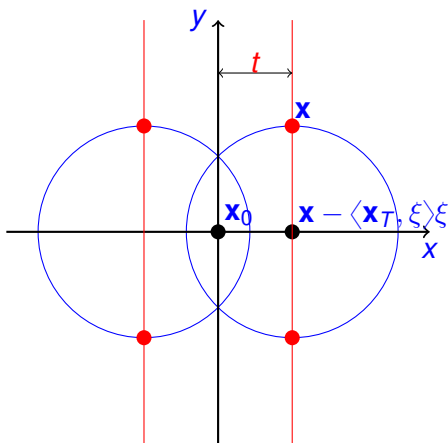
Therefore, artifacts can appear in the reconstruction along rings which are the intersections of apples and the cylinder of radius  $t$  with the same axis of revolution.

## 2-D cross-section of a spindle torus with this cylinder.



The cylinder intersects the apple along rings at the top and bottom of the apple. The red points on the apple are where  $\Pi_L$  drops rank.

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*The cylinder never intersects the lemon, so Bolker holds for  $\mathcal{L}_T$ .*

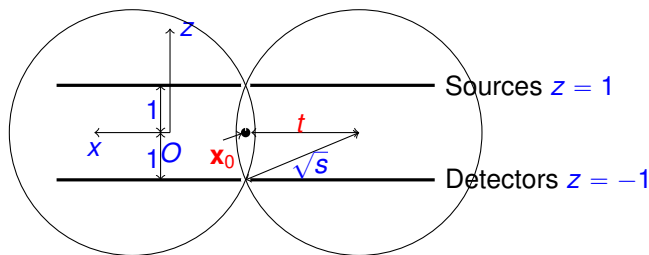
# A 3-dimensional geometry from luggage testing

We consider the practical geometry where the sources are on the plane  $z = 1$  and the detectors are on the plane  $z = -1$   
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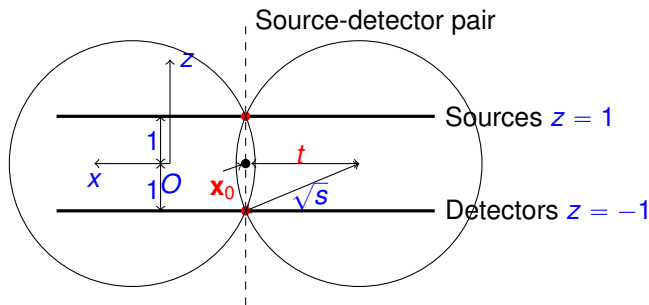
- ▶  $\mathbf{x}_0 \in \mathbb{R}^2$ :  $(\mathbf{x}_0, 0)$  is the center of the spindle torus
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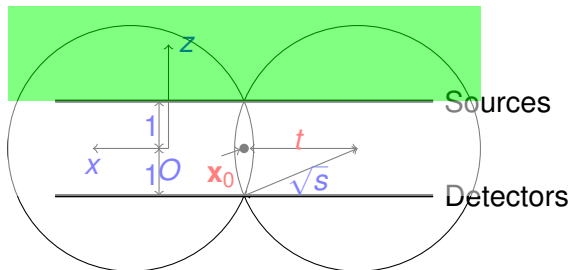
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- ▶ The detector is directly below the source and they move together.



# The transforms for luggage testing

$$\mathcal{A}_0 f_1(t, \mathbf{x}_0) = \mathcal{A} f(t^2 + 1, t, (\mathbf{x}_0, 0)^T, \mathbf{e}_3)$$

1.  $\mathcal{A}_0$  is an FIO for compactly supported distributions on  $\{z > 1\}$  (above the detector array)—or below.



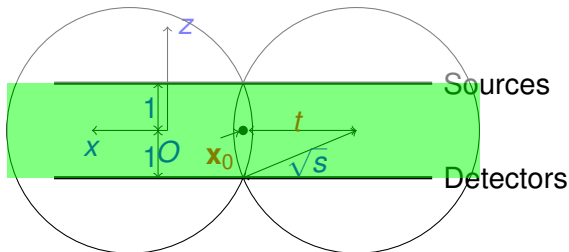
# The transforms for luggage testing

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and

$$\mathcal{L}_0 f(t, \mathbf{x}_0) = \mathcal{L}f \left( t^2 + 1, t, (x_0, y_0, 0)^T, \mathbf{e}_3 \right).$$

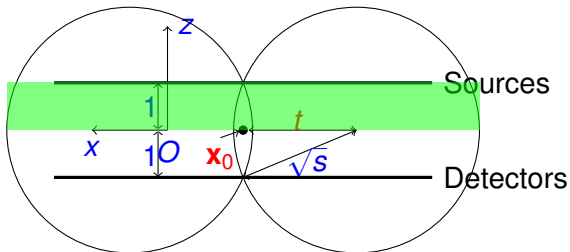
1.  $\mathcal{A}_0$  is an FIO for compactly supported distributions on  $\{z > 1\}$  (above the detector array)—or below.
2.  $\mathcal{L}_0$  is an FIO for compactly supported distributions on  $\{-1 < z < 1\}$  (in-between the source and detector array).





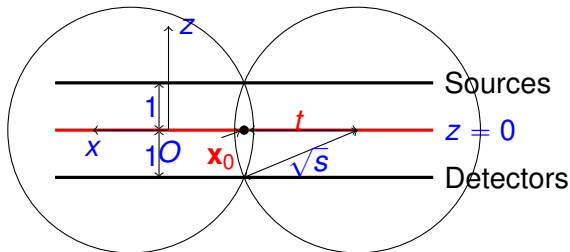
## Theorem

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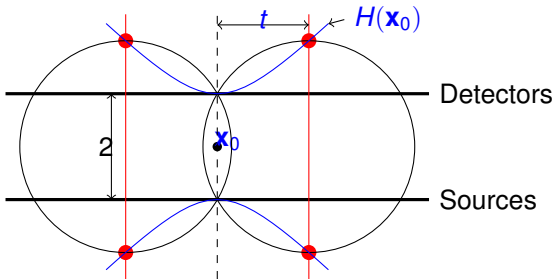
On  $\{-1 < z < 1\}$ , artifacts occur at mirror points—reflections in  $z = 0$

## Theorem

- ▶ The apple transform  $\mathcal{A}_0$  satisfies Bolker for distributions supported in the region above the hyperboloid

$$H(\mathbf{x}_0) = \{(x, y, z) : z^2 - 1 = (x - x_0)^2 + (y - y_0)^2\}$$

$\Pi_L$  drops rank at the red points where the apple intersects  $H(\mathbf{x}_0)$ .

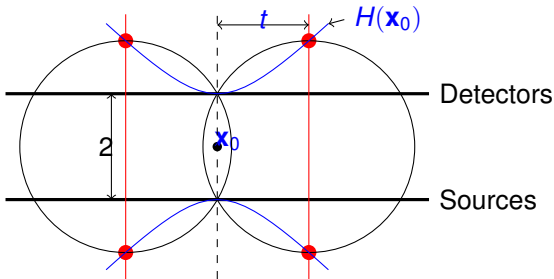


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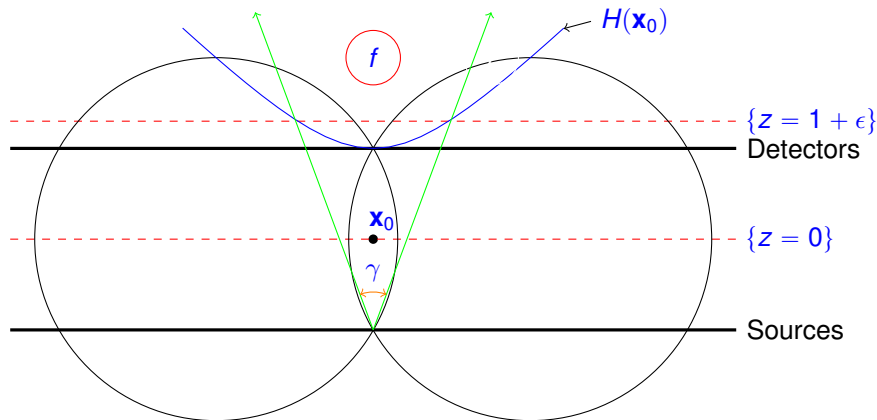
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**Warning:** This region where Bolker holds depends on  $\mathbf{x}_0$ !

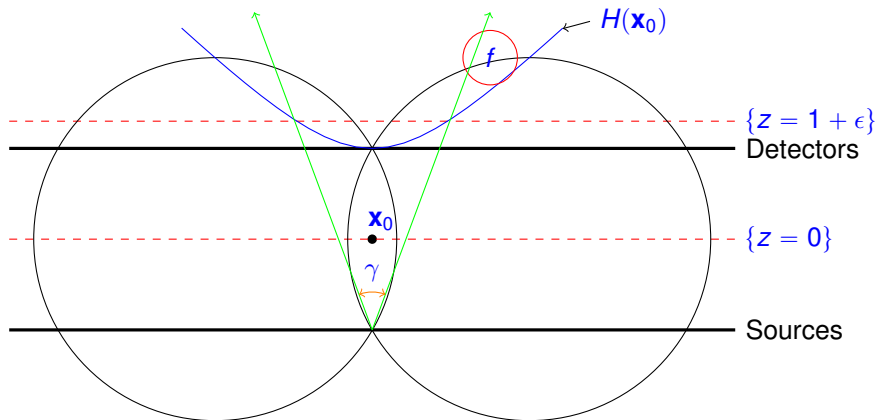
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As the source and detector pairs move, only the part of  $\text{supp}(f)$  above  $H(\mathbf{x}_0)$  is illuminated.

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*Thanks for listening!*

# References

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