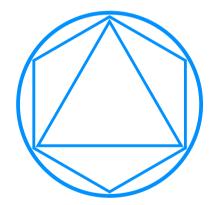
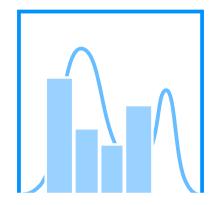
# Multivariate Lévy driven Stochastic Volatility Models

Robert Stelzer



Chair of Mathematical Statistics Zentrum Mathematik Technische Universität München email: rstelzer@ma.tum.de

http://www.ma.tum.de/stat/



#### Parts based on joint work with O. E. Barndorff-Nielsen and Ch. Pigorsch

### Outline of this talk

- Motivation from finance and the univariate model
- Matrix subordinators
- Positive semi-definite Ornstein-Uhlenbeck type processes (based on Barndorff-Nielsen & St., 2007; Pigorsch & St., 2008a)
- Multivariate Ornstein-Uhlenbeck type stochastic volatility model (based on Pigorsch & St., 2008b)
- Multivariate COGARCH(1,1) (based on St., 2008)

## **Stylized Facts of Financial Return Data**

- non-constant, stochastic volatility
- volatility exhibits jumps
- asymmetric and heavily tailed marginal distributions
- clusters of extremes
- log returns exhibit marked dependence, but have vanishing autocorrelations (squared returns, for instance, have non-zero autocorrelation)

Stochastic Volatility Models are used to cover these stylized facts.

### Univariate BNS Model I

• Logarithmic stock price process  $(Y_t)_{t \in \mathbb{R}^+}$ :

$$dY_t = (\mu + \beta \sigma_{t-}) dt + \sigma_{t-}^{1/2} dW_t$$

with parameters  $\mu, \beta \in \mathbb{R}$  and  $(W_t)_{t \in \mathbb{R}^+}$  being standard Brownian motion.

• Ornstein-Uhlenbeck-type volatility process  $(\sigma_t)_{t \in \mathbb{R}^+}$ :

$$d\sigma_t = -\lambda \sigma_t - dt + dL_t, \ \sigma_0 > 0$$

with parameter  $\lambda > 0$  and  $(L_t)_{t \in \mathbb{R}^+}$  being a Lévy subordinator.

## Univariate BNS Model II

• Usually  $E(\max(\log |L_1|, 0)) < \infty$  and  $\sigma$  is chosen as the unique stationary solution to  $d\sigma_t = -\lambda \sigma_{t-} dt + dL_t$  given by

$$\sigma_t = \int_{-\infty}^t e^{-\lambda(t-s)} dL_s.$$

• Closed form expression for the integrated volatility

$$\int_0^t \sigma_s ds = \frac{1}{\lambda} \left( L_t - \sigma_t + \sigma_0 \right).$$

Derivative Pricing via Laplace transforms possible.

## **The Need for Multivariate Models**

Multivariate models are needed

- to study comovements and spill over effects between several assets.
- for optimal portfolio selection and risk management at a portfolio level.
- to price derivatives on multiple assets.

#### Desire:

Multivariate models that are flexible, realistic and analytically tractable.

## **Some Matrix Notation**

- $M_d(\mathbb{R})$ : the real  $d \times d$  matrices.
- $\mathbb{S}_d$ : the real symmetric  $d \times d$  matrices.
- $\mathbb{S}_d^+$ : the positive-semidefinite  $d \times d$  matrices (covariance matrices) (a closed cone).
- $\mathbb{S}_d^{++}$ : the positive-definite  $d \times d$  matrices (an open cone).
- $A^{1/2}$ : for  $A \in \mathbb{S}_d^+$  the unique positive-semidefinite square root (functional calculus).

### Matrix Subordinators

• Definition:

An  $\mathbb{S}_d$ -valued Lévy process L is said to be a *matrix subordinator*, if  $L_t - L_s \in \mathbb{S}_d^+$  for all  $s, t \in \mathbb{R}^+$  with t > s. (Barndorff-Nielsen and Pérez-Abreu (2008)).

- The paths are  $\mathbb{S}_d^+$ -increasing and of finite variation.
- The characteristic function  $\mu_{L_t}$  of  $L_t$  for  $t \in \mathbb{R}^+$  is given by

$$\mu_{L_t}(Z) = \exp\left(t\left(i\mathrm{tr}(\gamma_L Z) + \int_{\mathbb{S}_d^+ \setminus \{0\}} \left(e^{i\mathrm{tr}(XZ)} - 1\right)\nu_L(dX)\right)\right), \ Z \in \mathbb{S}_d,$$

where  $\gamma_L$  is the drift and  $\nu_L$  the Lévy measure.

### **Examples of Matrix Subordinators**

- Analogues of univariate subordinators can be defined via the characteristic functions: e.g. (tempered) stable, Gamma or IG matrix subordinators
- Diagonal matrix subordinators, i.e. off-diagonal elements zero, diagonal elements univariate subordinators
- Discontinuous part of the Quadratic (Co-)Variation process of any *d*dimensional Lévy process *L*:

$$[\tilde{L}, \tilde{L}]_t^{\mathfrak{d}} = \sum_{s \le t} \Delta \tilde{L}_s (\Delta \tilde{L}_s)^T$$

## Linear Operators Preserving Positive-Semidefiniteness

**Proposition** Let  $\mathbf{A} : \mathbb{S}_d \to \mathbb{S}_d$  be a linear operator. Then  $e^{\mathbf{A}t}(\mathbb{S}_d^+) = \mathbb{S}_d^+$  for all  $t \in \mathbb{R}$ , if and only if  $\mathbf{A}$  is representable as  $X \mapsto AX + XA^T$  for some  $A \in M_d(\mathbb{R})$ .

One has  $e^{\mathbf{A}t}X = e^{At}Xe^{A^{T}t}$  for all  $X \in \mathbb{S}_{d}$ .

In the above setting  $\sigma(\mathbf{A}) = \sigma(A) + \sigma(A)$ . Hence, **A** has only eigenvalues of strictly negative real part, if and only if this is the case for *A*.

## **Positive-semidefinite OU-type Processes**

**Theorem** Let  $(L_t)_{t \in \mathbb{R}}$  be a matrix subordinator with  $E(\max(\log ||L_1||, 0)) < \infty$ and  $A \in M_d(\mathbb{R})$  such that  $\sigma(A) \subset (-\infty, 0) + i\mathbb{R}$ .

Then the stochastic differential equation of Ornstein-Uhlenbeck-type

$$d\Sigma_t = (A\Sigma_{t-} + \Sigma_{t-}A^T)dt + dL_t$$

has a unique stationary solution

$$\Sigma_t = \int_{-\infty}^t e^{A(t-s)} dL_s e^{A^T(t-s)}$$

or, in vector representation,  $\operatorname{vec}(\Sigma_t) = \int_{-\infty}^t e^{(I_d \otimes A + A \otimes I_d)(t-s)} d\operatorname{vec}(L_s)$ . Moreover,  $\Sigma_t \in \mathbb{S}_d^+$  for all  $t \in \mathbb{R}$ .

## **Stationary Distribution**

**Theorem** Let  $\gamma_L$  be the drift of the driving matrix subordinator *L* and  $\nu_L$  its Lévy measure.

The stationary distribution of the Ornstein-Uhlenbeck process  $\Sigma$  is infinitely divisible (even operator self-decomposable) with characteristic function

$$\hat{\mu}_{\Sigma}(Z) = \exp\left(i\mathrm{tr}(\gamma_{\Sigma}Z) + \int_{\mathbb{S}_{d}^{+}\setminus\{0\}} (e^{i\mathrm{tr}(YZ)} - 1)\nu_{\Sigma}(dY)\right), \ Z \in \mathbb{S}_{d},$$

where

$$\gamma_{\Sigma} = -\mathbf{A}^{-1}\gamma_L$$
 and  $\nu_{\Sigma}(E) = \int_0^\infty \int_{\mathbb{S}_d^+ \setminus \{0\}} I_E(e^{As}xe^{A^Ts})\nu_L(dx)ds$ 

for all Borel sets E in  $\mathbb{S}_d^+ \setminus \{0\}$ .

 $A^{-1}$  is the inverse of the linear operator  $A : \mathbb{S}_d(\mathbb{R}) \to \mathbb{S}_d(\mathbb{R}), X \mapsto AX + XA^T$ which can be represented as  $\operatorname{vec}^{-1} \circ ((I_d \otimes A) + (A \otimes I_d))^{-1} \circ \operatorname{vec}$ .

#### **Strict Positive-definiteness**

**Proposition** If  $\gamma_L \in \mathbb{S}_d^{++}$  or  $\nu_L(\mathbb{S}_d^{++}) > 0$ , then the stationary distribution  $P_{\Sigma}$  of  $\Sigma$  is concentrated on  $\mathbb{S}_d^{++}$ , i.e.  $P_{\Sigma}(\mathbb{S}_d^{++}) = 1$ .

**Theorem** Let  $\tilde{L}$  be a Lévy process in  $\mathbb{R}^d$  with Lévy measure  $\nu_{\tilde{L}} \neq 0$  and assume that  $\nu_{\tilde{L}}$  is absolutely continuous (with respect to the Lebesgue measure on  $\mathbb{R}^d$ ).

Then the stationary distribution of the Ornstein-Uhlenbeck type process  $\Sigma_t$ driven by the discontinuous part of the quadratic variation  $[\tilde{L}, \tilde{L}]_t^{\mathfrak{d}}$  is absolutely continuous with respect to the Lebesgue measure. Moreover, the stationary distribution  $P_{\Sigma}$  of  $\Sigma_t$  is concentrated on  $\mathbb{S}_d^{++}$ , i.e.  $P_{\Sigma}(\mathbb{S}_d^{++}) = 1$ .

### **Marginal Dynamics**

Assume that A is real diagonalisable and let  $U \in GL_d(\mathbb{R})$  be such that  $UAU^{-1} =: D$  is diagonal.

•  $M_t := UL_t U^T$  is again a matrix subordinator.

• 
$$(U\Sigma_t U^T)_{ij} = \left(\int_{-\infty}^t e^{D(t-s)} d(UL_s U^T) e^{D(t-s)}\right)_{ij} = \int_{-\infty}^t e^{(\lambda_i + \lambda_j)(t-s)} dM_{ij,s}.$$

• Hence, the individual components of  $U\Sigma_t U^T$  are stationary onedimensional Ornstein-Uhlenbeck type processes with associated SDE  $d(U\Sigma_t U^T)_{ij} = (\lambda_i + \lambda_j)(U\Sigma_t U^T)_{ij}dt + dM_{ij,t}.$ 

 $M_{ii}$  for  $1 \le i \le d$  are necessarily subordinators and  $(U\Sigma_t U^T)_{ii}$  have to be positive OU type processes.

The individual components Σ<sub>ij,t</sub> of Σ<sub>t</sub> are superpositions of (at most d<sup>2</sup>) univariate OU type processes. The individual OU processes superimposed are in general not independent.

#### Second Order Structure

**Theorem** Assume that the driving Lévy process is square-integrable. Then the second order moment structure is given by

$$E(\Sigma_t) = \gamma_{\Sigma} - \mathbf{A}^{-1} \int_{\mathbb{S}_d^+ \setminus \{0\}} y\nu(dy) = -\mathbf{A}^{-1} E(L_1)$$
$$\operatorname{var}(\operatorname{vec}(\Sigma_t)) = -\mathcal{A}^{-1} \operatorname{var}(\operatorname{vec}(L_1))$$
$$\operatorname{cov}(\operatorname{vec}(\Sigma_{t+h}), \operatorname{vec}(\Sigma_t)) = e^{(A \otimes I_d + I_d \otimes A)h} \operatorname{var}(\operatorname{vec}(\Sigma_t)),$$

where  $t \in \mathbb{R}$  and  $h \in \mathbb{R}^+$ ,  $\mathbf{A} : M_d(\mathbb{R}) \to M_d(\mathbb{R}), X \mapsto AX + XA^T$  and  $\mathcal{A} : M_{d^2}(\mathbb{R}) \to M_{d^2}(\mathbb{R}), X \mapsto (A \otimes I_d + I_d \otimes A)X + X(A^T \otimes I_d + I_d \otimes A^T).$ 

The individual components of the autocovariance matrix do not have to decay exponentially, but may exhibit exponentially damped sinusoidal behaviour.

### **The Integrated Volatility**

**Theorem** The integrated Ornstein-Uhlenbeck process  $\Sigma_t^+$  is given by

$$\Sigma_t^+ := \int_0^t \Sigma_t dt = \mathbf{A}^{-1} \left( \Sigma_t - \Sigma_0 - L_t \right)$$

for  $t \in \mathbb{R}^+$ .

## Multivariate OU type Stochastic Volatility Model

*d*-dimensional logarithmic stock price process  $(Y_t)_{t \in \mathbb{R}}$ :

$$dY_t = (\mu + \Sigma_{t-}\beta) dt + \Sigma_{t-}^{1/2} dW_t$$

with

17

- $(W_t)_{t \in \mathbb{R}^+}$  being *d*-dimensional standard Brownian motion,
- $\mu, \beta \in \mathbb{R}^d$  and
- $(\Sigma_t)_{t \in \mathbb{R}^+}$  being a stationary  $\mathbb{S}_d^+$ -valued Ornstein-Uhlenbeck type process.

#### $\implies$ Natural analogue of the univariate model

#### **The Conditional Fourier Transform**

Assume the driving matrix subordinator L has characteristic exponent  $\psi_L$ , i.e.  $E(e^{i\operatorname{tr}(L_t z)}) = e^{t\psi_L(z)}$  for all  $z \in M_d(\mathbb{R}) + i\mathbb{S}_d^+$ . Let  $(Y_0, \Sigma_0) \in \mathbb{R}^d \times \mathbb{S}_d^+$  be the initial values. Then we have for every  $t \in \mathbb{R}^+$  and  $(y, z) \in \mathbb{R}^d \times M_d(\mathbb{R})$ 

$$E\left(e^{i\left(Y_{t}^{T}y+\operatorname{tr}(\Sigma_{t}z)\right)}\middle|\Sigma_{0},Y_{0}\right) = \exp\left\{i(Y_{0}+\mu t)^{T}y+i\operatorname{tr}\left(\Sigma_{0}e^{A^{T}t}ze^{At}\right)\right.$$
$$\left.+i\operatorname{tr}\left(\Sigma_{0}e^{A^{T}t}\left[\mathbf{A}^{-*}\left(y\beta^{T}+\frac{i}{2}yy^{T}\right)\right]e^{At}-\Sigma_{0}\left[\mathbf{A}^{-*}\left(y\beta^{T}+\frac{i}{2}yy^{T}\right)\right]\right)\right.$$
$$\left.+\int_{0}^{t}\psi_{L}\left(e^{A^{T}s}ze^{As}+e^{A^{T}s}\left[\mathbf{A}^{-*}\left(y\beta^{T}+\frac{i}{2}yy^{T}\right)\right]e^{As}-\mathbf{A}^{-*}\left(y\beta^{T}+\frac{i}{2}yy^{T}\right)\right)ds\right\}$$

with  $A^{-*}$  denoting the inverse of the adjoint of A, i.e.  $A^{-*}$  is the inverse of the linear operator  $A^*$  given by  $X \mapsto A^T X + X A$ .

### **The Logarithmic Returns**

Let  $\Delta > 0$  (grid size). Define for  $n \in \mathbb{N}$ :

• log-returns over periods  $[(n-1)\Delta, n\Delta]$  of length  $\Delta$ :

$$\mathbf{Y}_{n} = Y_{n\Delta} - Y_{(n-1)\Delta} = \int_{(n-1)\Delta}^{n\Delta} (\mu + \Sigma_{t}\beta) dt + \int_{(n-1)\Delta}^{n\Delta} \Sigma_{t}^{1/2} dW_{t}.$$

• Integrated volatility over  $[(n-1)\Delta, n\Delta]$ :

$$\boldsymbol{\Sigma}_{\boldsymbol{n}} := \int_{(n-1)\Delta}^{n\Delta} \Sigma_t dt.$$

It holds that

$$\mathbf{Y}_n \left| \mathbf{\Sigma}_n \sim N_d \left( \mu \Delta + \mathbf{\Sigma}_n \beta, \mathbf{\Sigma}_n \right) \right|$$

with  $N_d$  denoting the *d*-dimensional normal distribution.

### Second Order Structure of $\Sigma_n$

Assume henceforth  $E(||L_1||^2) < \infty$ .

$$E(\mathbf{\Sigma}_{n}) = \Delta E(\Sigma_{0}) = -\Delta \mathbf{A}^{-1} E(L_{1})$$
  

$$\operatorname{var}(\operatorname{vec}(\mathbf{\Sigma}_{n})) = r^{++}(\Delta) + (r^{++}(\Delta))^{T}$$
  

$$r^{++}(t) = (\mathscr{A}^{-2} (e^{\mathscr{A}t} - I_{d^{2}}) - \mathscr{A}^{-1}t) \operatorname{var}(\operatorname{vec}(\Sigma_{0}))$$
  

$$= -(\mathscr{A}^{-2} (e^{\mathscr{A}t} - I_{d^{2}}) - \mathscr{A}^{-1}t))\mathcal{A}^{-1}\operatorname{var}(\operatorname{vec}(L_{1}))$$
  

$$\operatorname{acov}_{\mathbf{\Sigma}}(h) = e^{\mathscr{A}\Delta(h-1)}\mathscr{A}^{-2} (I_{d^{2}} - e^{\mathscr{A}\Delta})^{2} \operatorname{var}(\operatorname{vec}(\Sigma_{0}))$$
  

$$= -e^{\mathscr{A}\Delta(h-1)}\mathscr{A}^{-2} (I_{d^{2}} - e^{\mathscr{A}\Delta})^{2} \mathcal{A}^{-1}\operatorname{var}(\operatorname{vec}(L_{1})), h \in \mathbb{N}.$$

where  $\mathscr{A} = A \otimes I_d + I_d \otimes A$  and  $\mathcal{A} : M_{d^2}(\mathbb{R}) \to M_{d^2}(\mathbb{R}), X \mapsto \mathscr{A}X + X \mathscr{A}^T$ .

 $\implies$  vec $(\Sigma_n)$  is a causal ARMA(1,1) process with AR parameter  $e^{\mathscr{A}\Delta}$ .

## Second Order Structure of $\mathbf{Y}_n$ and $\mathbf{Y}_n \mathbf{Y}_n^T$

$$E(\mathbf{Y}_n) = (\mu + E(\Sigma_0)\beta)\Delta$$
  

$$\operatorname{var}(\mathbf{Y}_n) = E(\Sigma_0)\Delta + (\beta^T \otimes I_d)\operatorname{var}(\operatorname{vec}(\mathbf{\Sigma}_n))(\beta \otimes I_d)$$
  

$$\operatorname{acov}_{\mathbf{Y}}(h) = (\beta^T \otimes I_d)\operatorname{acov}_{\mathbf{\Sigma}}(h)(\beta \otimes I_d), h \in \mathbb{N}$$

Assume  $\mu = \beta = 0$ . Then:

$$E(\mathbf{Y}_{n}\mathbf{Y}_{n}^{T}) = E(\Sigma_{0})\Delta$$
  
var(vec( $\mathbf{Y}_{n}\mathbf{Y}_{n}^{T}$ )) =  $(I_{d^{2}} + \mathbf{Q} + \mathbf{P}\mathbf{Q})$  var(vec( $\Sigma_{n}$ ))  
 $+(I_{d^{2}} + \mathbf{P}) (E(\Sigma_{0}) \otimes E(\Sigma_{0})) \Delta^{2}$   
acov<sub>**YY**</sub> $(h)$  = acov<sub>**\Sigma**</sub> $(h)$  for  $h \in \mathbb{N}$ 

where **P** and **Q** are linear operators on  $M_{d^2}(\mathbb{R})$  rearranging the entries.

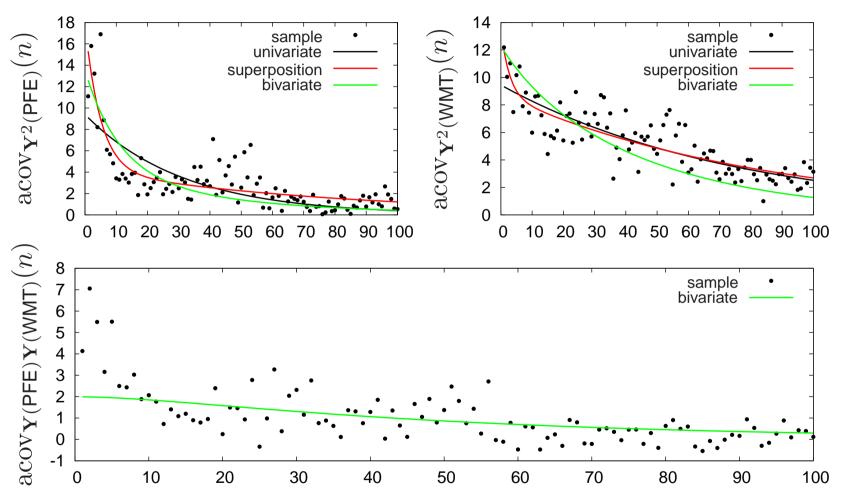
 $\implies$  vec $(\mathbf{Y}_n \mathbf{Y}_n^T)$  is a causal ARMA(1,1) process with AR parameter  $e^{\mathscr{A}\Delta}$ .

### **Moment Estimators**

- Assume  $\mu = \beta = 0$
- $E(L_1)$ ,  $var(vec(L_1))$  and A can be estimated from the empirically observed  $E(\mathbf{Y}_n \mathbf{Y}_n^T)$ ,  $acov_{\mathbf{Y}\mathbf{Y}^T}(1)$  and  $acov_{\mathbf{Y}\mathbf{Y}^T}(2)$ .
- They are identified provided one assumes that  $e^{\mathbf{A}_{vech}\Delta}$  has a unique real logarithm and  $var(vech(\Sigma_0))$  is invertible.
- In practice one uses more lags of the autocovariance function and GMM estimation.
- The log-returns Y are strongly mixing. Thus the estimators are under appropriate technical conditions consistent and asymptotically normal.



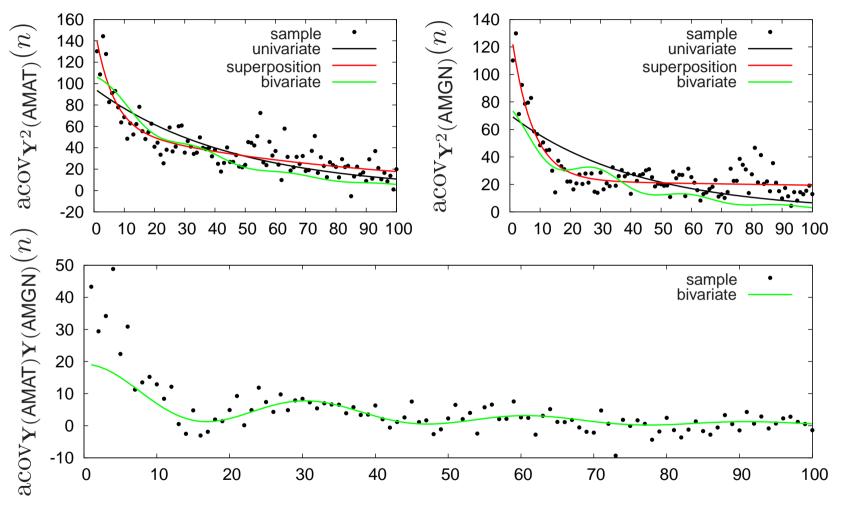
#### **Empirical Illustration I**



Empirical and estimated autocovariance functions: PFE and WMT



#### **Empirical Illustration II**



Empirical and estimated autocovariance functions: AMAT and AMGN

## **Extensions**

Even more flexibility (and long memory) by considering superpositions of independent multivariate positive semi-definite OU type processes for  $\Sigma$ . Possibilities:

- Superposition of finitely many OU type processes: Straightforward and (almost) all results easily extendible.
- Superposition of countably many OU type processes and convergence in  $L^2$ .
- Use of a  $\mathbb{S}_d^+$ -valued Lévy basis  $\Lambda$  on  $\mathbb{R} \times M_d^-(\mathbb{R})$  with  $M_d^-(\mathbb{R}) := \{X \in M_d(\mathbb{R}) : \sigma(X) \subset (-\infty, 0) + i\mathbb{R}\}$ :

$$\Sigma_t = \int_{-\infty}^t \int_{M_d^-(\mathbb{R})} e^{A(t-s)} \Lambda(ds, dA) e^{A^T(t-s)}$$

## **Univariate BNS and COGARCH model**

• The Ornstein-Uhlenbeck type stochastic volatility model (BNS model):

$$dY_t = \sqrt{\sigma_{t-}} dW_t$$
$$d\sigma_t = -\lambda \sigma_{t-} dt + dL_t$$

with  $\lambda > 0$ , W standard Brownian motion and L a subordinator.

• The COGARCH(1,1) model (Klüppelberg, Lindner, Maller (2004)):

$$\begin{split} dY_t &= \sqrt{\sigma_{t-}} dL_t \\ \sigma_t &= c + v_t, \quad dv_t = -\alpha v_{t-} dt + \beta \sigma_{t-} d[L,L]_t^{\mathfrak{d}} \end{split}$$

with  $\alpha, \beta, c > 0$ , L a Lévy process and  $[L, L]_t^{\mathfrak{d}} = \sum_{0 < s < t} (\Delta L_s)^2$ .

## Multivariate COGARCH(1,1) – Definition

**Definition** Let *L* be a *d*-dimensional Lévy process and  $A, B \in M_d(\mathbb{R}), C \in \mathbb{S}_d^+$ and set  $[L, L]_t^{\mathfrak{d}} := \sum_{0 < s \leq t} \Delta L_s(\Delta L_s)^T$ . Then the process  $Y = (Y_t)_{t \in \mathbb{R}^+}$ solving

$$dY_t = \Sigma_{t-}^{1/2} dL_t, \qquad \Sigma_t = C + V_t, \tag{1}$$

$$dV_t = (AV_{t-} + V_{t-}A^T)dt + B\Sigma_{t-}^{1/2}d[L,L]_t^{\mathfrak{d}}\Sigma_{t-}^{1/2}B^T$$
(2)

with initial values  $Y_0 = 0$  in  $\mathbb{R}^d$  and  $V_0$  in  $\mathbb{S}_d^+$  is called a *multivariate COGARCH(1,1)* process.

The process  $V = (V_t)_{t \in \mathbb{R}^+}$  (or  $\Sigma$ ) with paths in  $\mathbb{S}_d^+$  is referred to as a *multivariate COGARCH(1,1) volatility process*.

Agrees with the definition of the COGARCH(1,1) for d = 1 and inherits many of the properties of multivariate GARCH(1,1).

## Multivariate COGARCH(1,1) – Equivalent Definitions

• One can directly define  $\Sigma$  via the SDE

 $d\Sigma_t = (A(\Sigma_{t-} - C) + (\Sigma_{t-} - C)A^T)dt + B\Sigma_{t-}^{1/2}d[L, L]_t^{\mathfrak{d}}\Sigma_{t-}^{1/2}B^T$ 

which shows that  $\Sigma$  has a mean reverting structure (provided  $\sigma(A) \subset (-\infty, 0) + i\mathbb{R}$ ) with "mean" *C*.

 The volatility process V (or Σ) is of finite variation and V satisfies for all t ∈ ℝ<sup>+</sup>

$$V_t = e^{At} V_0 e^{A^T t} + \int_0^t e^{A(t-s)} B \Sigma_{s-}^{1/2} d[L, L]_s^{\mathfrak{d}} \Sigma_{s-}^{1/2} B^T e^{A^T (t-s)}.$$

## **Markovian Properties and Stationarity**

Provided  $C \in \mathbb{S}_d^{++}$ , (Y, V) and V alone are temporally homogeneous strong Markov processes on  $\mathbb{R}^d \times \mathbb{S}_d^+$  and  $\mathbb{S}_d^+$ , respectively. Moreover, both have the weak Feller property.

Theorem 1. Assume:

- $C \in \mathbb{S}_d^{++}$ ,  $A \in M_d(\mathbb{R})$  is diagonalisable with  $S \in GL_d(\mathbb{C})$  such that  $S^{-1}AS$  is diagonal,
- the Lévy measure  $\nu_L$  of L satisfies

 $\int_{\mathbb{R}^d} \log \left( 1 + \alpha_1 \| (S^{-1} \otimes S^{-1}) \operatorname{vec}(yy^T) \|_2 \right) \nu_L(dy) < -2 \max(\Re(\sigma(A))),$ where  $\alpha_1 := \|S\|_2^2 \|S^{-1}\|_2^2 K_{2,A} \| (S^{-1}BS) \otimes (S^{-1}BS) \|_2,$  $K_{2,A} := \max_{X \in \mathbb{S}^+_d, \|X\|_2 = 1} \left( \frac{\|X\|_2}{\|(S^{-1} \otimes S^{-1}) \operatorname{vec}(X)\|_2} \right).$  Then there exists a stationary distribution  $\mu$  for the multivariate COGARCH(1,1) volatility process V having the following property:

lf

$$\int_{\mathbb{R}^d} \left( \left( 1 + \alpha_1 \| (S^{-1} \otimes S^{-1}) \operatorname{vec}(yy^T) \|_2 \right)^k - 1 \right) \nu_L(dy) < -2k \max(\Re(\sigma(A)))$$

for some 
$$k \in \mathbb{N}$$
, then

$$\int_{\mathbb{S}_d^+} \|x\|^k \mu(dx) < \infty,$$

#### i.e. the *k*-th moment of $\mu$ is finite.

The stationary distribution is not known to be unique or to be a limiting distribution.

#### **Second Order Properties**

Assume:

• The driving Lévy process *L* has finite fourth moments and  $\nu_L$  satisfies

$$\int_{\mathbb{R}^d} x x^T \nu_L(dx) = \sigma_L I_d,$$
  
$$\int_{\mathbb{R}^d} \operatorname{vec}(x x^T) \operatorname{vec}(x x^T)^T \nu_L(dx) = \rho_L(I_{d^2} + K_d + \operatorname{vec}(I_d) \operatorname{vec}(I_d)^T)$$

for some  $\sigma_L, \rho_L \in \mathbb{R}^+$  and with  $K_d$  being the commutation matrix,

•  $\sigma(A), \sigma(\mathscr{A}), \sigma(\mathscr{C}) \subset (-\infty, 0) + i\mathbb{R}$  with

 $\mathscr{A} = A \otimes I_d + I_d \otimes A + \sigma_L B \otimes B,$ 

 $\mathscr{C} := \mathscr{A} \otimes I_{d^2} + I_{d^2} \otimes \mathscr{A} + \sigma_L \left( (B \otimes B) \otimes I_{d^2} + I_{d^2} \otimes (B \otimes B) \right) + \mathscr{BR},$ 

 $\mathscr{B} = (B \otimes B) \otimes (B \otimes B), \ \mathcal{R} = \rho_L \left( \mathcal{Q} + \mathcal{K}_d \mathcal{Q} + I_{d^4} \right),$ 

where  $\mathcal{K}_d$  and  $\mathcal{Q}$  are certain permutation matrices.

•  $V_0$  has finite second moments.

#### Then V is asymptotically second order stationary with

• mean

$$E(\operatorname{vec}(V_{\infty})) = -\sigma_L \mathscr{A}^{-1}(B \otimes B)\operatorname{vec}(C),$$

• autocovariance function

$$\operatorname{acov}_{\operatorname{vec}(V_{\infty})}(h) = e^{\mathscr{A}h}\operatorname{var}(\operatorname{vec}(V_{\infty}))$$

for  $h \in \mathbb{R}^+$ 

• and variance

 $\operatorname{vec}(\operatorname{vec}(V_{\infty}))) = -\mathscr{C}^{-1}\left[\left(\sigma_{L}^{2}\mathscr{C}(\mathscr{A}^{-1}\otimes\mathscr{A}^{-1})\mathscr{B} + \mathscr{B}\mathscr{R}\right)\left(\operatorname{vec}(C)\otimes\operatorname{vec}(C)\right) + \left(\sigma_{L}(B\otimes B)\otimes I_{d^{2}} + \mathscr{B}\mathscr{R}\right)\operatorname{vec}(C)\otimes E\left(\operatorname{vec}(V_{\infty})\right) + \left(\sigma_{L}I_{d^{2}}\otimes(B\otimes B) + \mathscr{B}\mathscr{R}\right)E\left(\operatorname{vec}(V_{\infty})\right)\otimes\operatorname{vec}(C)\right].$ 

#### The Increments of $\boldsymbol{Y}$

For  $\Delta > 0$  the sequence of increments  $\mathbf{Y} = (\mathbf{Y}_n)_{n \in \mathbb{N}}$  defined by

$$\mathbf{Y}_n = \int_{(n-1)\Delta}^{n\Delta} \Sigma_{s-}^{1/2} dL_s$$

gives the log-returns over consecutive time periods of length  $\Delta$  in a financial context.

#### **Stationarity:**

If  $\Sigma$  (or V) is stationary, then **Y** is stationary.

## Stationary Second Order Structure of the ("Squared") Increments

Assume that the previous assumptions regarding the second order behaviour are satisfied and  $E(L_1) = 0$ ,  $var(L_1) = (\sigma_L + \sigma_W)I_d$  for some  $\sigma_W \in \mathbb{R}^+$ , then:

•  $(\mathbf{Y}_n)_{n \in \mathbb{N}}$  has finite fourth moments, mean zero and is uncorrelated. The increments **Y** are white noise with variance:

$$\operatorname{vec}(\operatorname{var}(\mathbf{Y}_1)) = (\sigma_L + \sigma_W) \Delta \mathscr{A}^{-1} (A \otimes I_d + I_d \otimes A) \operatorname{vec}(C)$$

• but the sequence of "squared" increments  $(\mathbf{Y}_n \mathbf{Y}_n^T)_{n \in \mathbb{N}}$  has non-zero autocorrelations which decrease exponentially (from lag one onwards):

$$\operatorname{acov}_{\mathbf{Y}\mathbf{Y}}(h) = e^{\mathscr{A}\Delta h} \mathscr{A}^{-1} \left( I_{d^2} - e^{-\mathscr{A}\Delta} \right) \left( \sigma_L + \sigma_W \right) \operatorname{cov}(\operatorname{vec}(V_\Delta), \operatorname{vec}(\mathbf{Y}_1\mathbf{Y}_1^*))$$

This is the autocovariance structure of an ARMA(1,1) process.

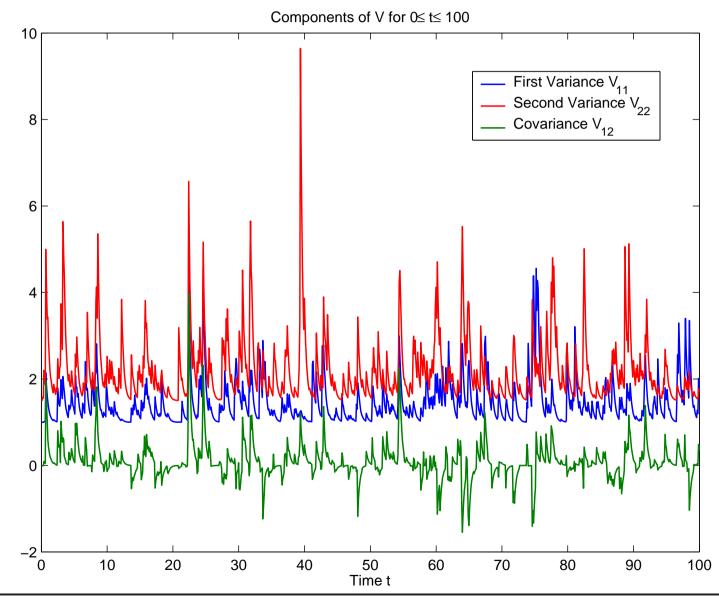
## **Illustrative Simulations**

In the following a simulation of a two-dimensional COGARCH(1,1) process is shown where:

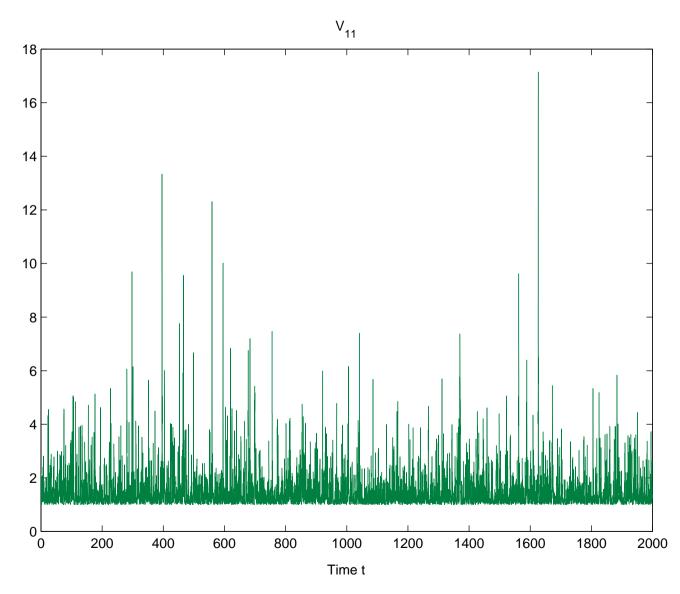
- the driving Lévy process is the sum of a standard Brownian motion and a compound Poisson process in  $\mathbb{R}^2$  with rate 4 and  $N(0, I_2/4)$ -distributed jumps.
- Hence,  $[L, L]^{\mathfrak{d}}$  is a compound Poisson process with Wishart-distributed jumps.

• 
$$A = -1.6I_2$$
,  $B = I_2$  and  
 $C = \begin{pmatrix} 1 & 0 \\ 0 & 1.5 \end{pmatrix}$  (corresponds to a "mean" correlation of zero).

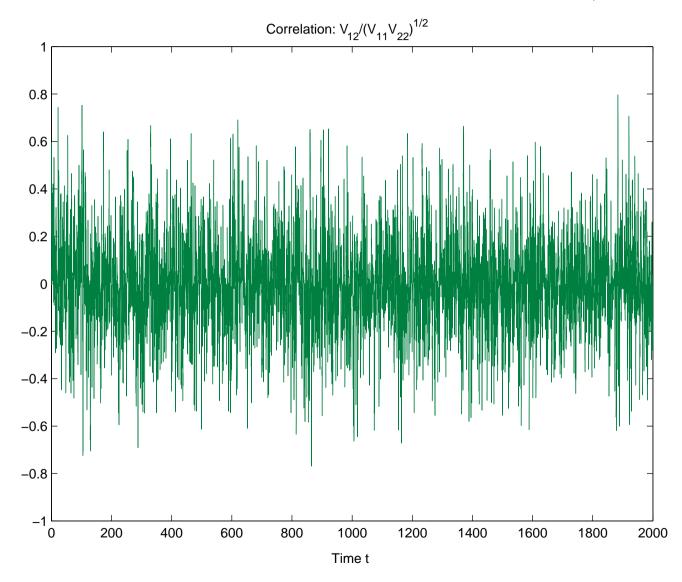
### Stochastic Volatility Process $\boldsymbol{\Sigma}$



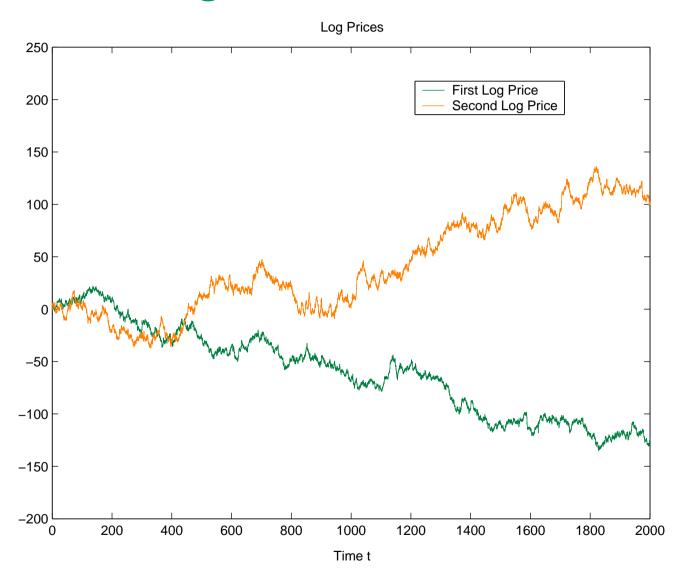
#### **First Stochastic Variance Process** $\Sigma_{11}$



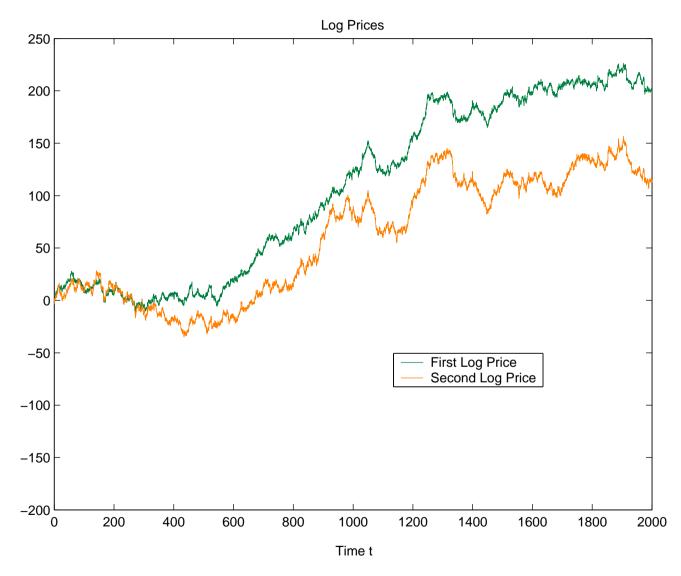
## **Stochastic Correlation Process** $\Sigma_{12}/\sqrt{\Sigma_{11}\Sigma_{22}}$



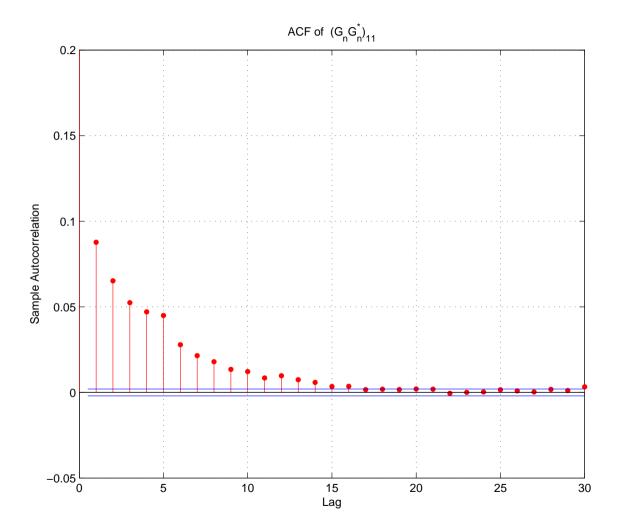
#### **Log-Price Process** Y



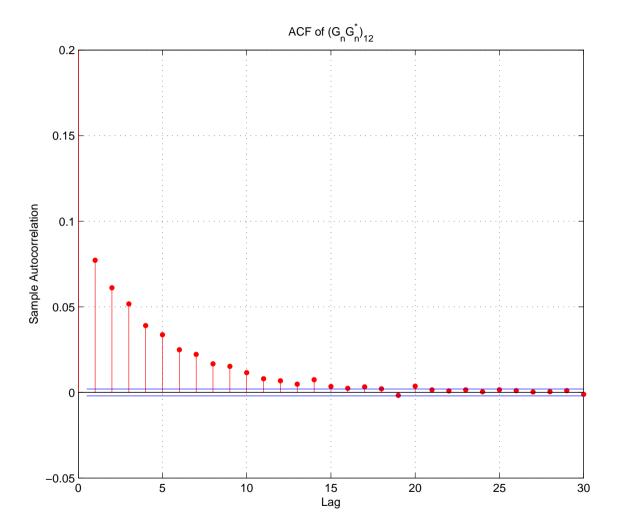
#### Alternative C: Log-Price Process Y



## ACF "Squared Returns" $(\mathbf{Y}\mathbf{Y}^T)_{11}$



## ACF "Squared Returns" $(\mathbf{Y}\mathbf{Y}^T)_{12}$



Thank you very much for your attention.