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# Diagonally symmetric polynomials of the roots of systems of polynomial equations

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## Fundamental Theorem of Symmetric Polynomials:

Fix  $d$ . For the polynomial equations

$$x^d + c_1 x^{d-1} + \cdots + c_{d-1}x + c_d = 0$$

the symmetric polynomials of the roots (in  $\mathbb{C}$ ) are exactly the polynomials in the coefficients  $c_1, \dots, c_{d-1}, c_d$ .

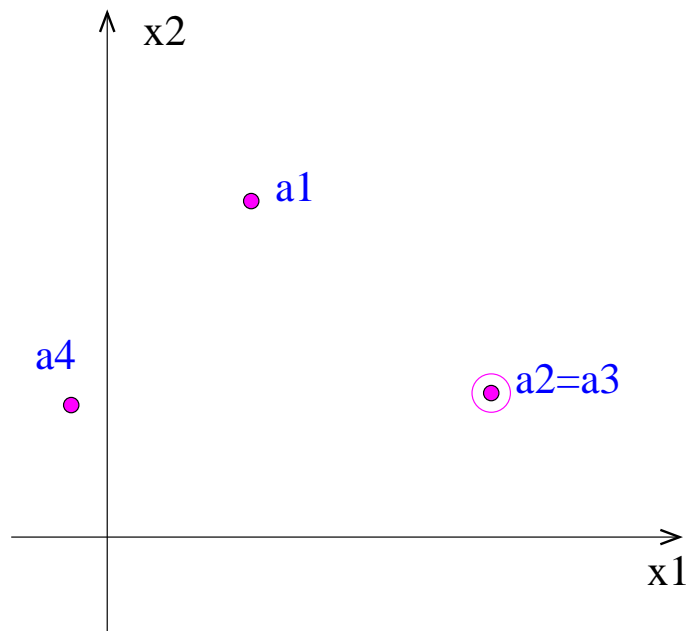
*What about systems of polynomial equations in several variables with finitely many solutions?*

The **diagonally symmetric polynomials** are the polynomials in the entries of the matrix

$$\begin{bmatrix} x_1(a_1) & x_1(a_2) & \cdots & x_1(a_n) \\ x_2(a_1) & x_2(a_2) & \cdots & x_2(a_n) \\ \vdots & \vdots & & \vdots \\ x_r(a_1) & x_r(a_2) & \cdots & x_r(a_n) \end{bmatrix}$$

that are invariant under all permutations of the columns.

They are the polynomial functions of multisets of  $n$  points,  $a_1, a_2, \dots, a_n$ , of the affine  $r$ -dimensional space !



**Ex:** the *diagonally symmetric power sums*

$$p_\alpha = \sum_{i=1}^n x^\alpha(a_i) = \sum_{i=1}^n (x_1^{\alpha_1} x_2^{\alpha_2} \cdots x_r^{\alpha_r})(a_i).$$

These objects appear naturally when studying systems of equations with finitely many solutions, e.g. as coefficients of the Chow form, as traces of monomials, or multidimensional residues . . .

They are not new !!! They were first introduced by Cayley, MacMahon, . . . in the XIX<sup>th</sup> century.

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ON THE SYMMETRIC FUNCTIONS OF THE ROOTS OF CERTAIN SYSTEMS OF TWO EQUATIONS.

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SUPPOSE in general that  $\phi = 0$ ,  $\psi = 0$ , &c. denote a system of  $(n - 1)$  equations between the  $n$  variables  $(x, y, z, \dots)$ , where the functions  $\phi$ ,  $\psi$ , &c. are quantics (i.e. rational and integral homogeneous functions) of the variables. Any values  $(x_1, y_1, z_1, \dots)$  satisfying the equations, are said to constitute a set of roots of the system; the roots of the same set are, it is clear, only determinate to a common factor *près*, i.e. only the ratios *inter se* and not the absolute magnitudes of the roots of a set are determinate. The number of sets, or the degree of the system, is equal to the product of the degrees of the component equations. Imagine a function of the roots which remains unaltered when any two sets  $(x_1, y_1, z_1, \dots)$  and  $(x_2, y_2, z_2, \dots)$  are interchanged (that is, when  $x_1$  and  $x_2$ ,  $y_1$  and  $y_2$ , &c. are simultaneously interchanged), and which is besides homogeneous of the same degree as regards each entire set of roots although

## The case of Gröbner bases

Let  $\mathbf{x} = (x_1, \dots, x_r)$ . Choose some monomial order, and monomials  $\mathbf{x}^{\alpha_1}, \mathbf{x}^{\alpha_2}, \dots, \mathbf{x}^{\alpha_r}$ , with among them a pure power of each variable.

Consider all systems

$$\begin{cases} F_1 = \mathbf{x}^{\alpha_1} + \textit{smaller terms} \\ F_2 = \mathbf{x}^{\alpha_2} + \textit{smaller terms} \\ \vdots \\ F_k = \mathbf{x}^{\alpha_k} + \textit{smaller terms} \end{cases}$$

that are a Gröbner basis.

**THEOREM** (E.B.): the diagonally symmetric polynomials of the roots of these systems are polynomial functions of the coefficients.

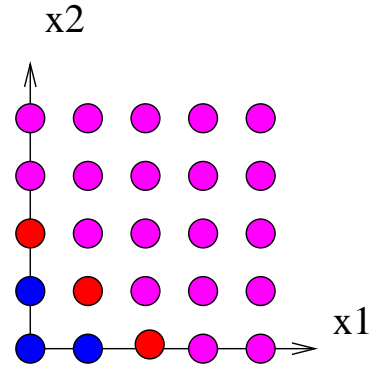
## An example:

Lexicographic degree order,

$$x_1 > x_2.$$

leading monomials:

$$x^{2,0}, x^{1,1}, x^{0,2}.$$



$$\begin{cases} F_1 = x_1^2 + b x_1 x_2 + c x_2^2 + d x_1 + e x_2 + f, \\ F_2 = x_1 x_2 + g x_2^2 + h x_1 + j x_2 + k, \\ F_3 = x_2^2 + q x_1 + s x_2 + t. \end{cases}$$

is a Gröbner basis iff

$$\begin{cases} f = -cs + es + dj + \text{other terms} \dots, \\ k = -gh^2 + jh - g^3 q^2 + \text{other terms} \dots, \\ t = -h^2 + qd + sh + \text{other terms} \dots \end{cases}$$

Then the system has  $n = 3$  zeros  $a_1, a_2, a_3$  in  $\mathbb{C}^2$ . One has, for instance, that the diagonally symmetric power sum

$$p_{11} = x^{1,1}(a_1) + x^{1,1}(a_2) + x^{1,1}(a_3)$$

admits as an expression

$$\begin{aligned} & -bh^2 + dh - jh - gs^2 - cqh \\ & + 3eq + gjq - 3bjq - 3cqs - g^2 qs - dgq \\ & + cq^2 g - bg^2 q^2 + 2bgqh + 3bgqs + ghs + js. \end{aligned}$$

If the zeros are all simple, one can find back the coefficients of the *reduced* Gröbner basis

$$\begin{cases} F_1 = x_1^2 & + d x_1 + e x_2 + f, \\ F_2 = x_1 x_2 & + h x_1 + j x_2 + k, \\ F_3 = x_2^2 & + q x_1 + s x_2 + t. \end{cases}$$

by means of *Lagrange interpolation*–like formulas, e.g.:

$$d = - \frac{\begin{vmatrix} 1 & x_2(a_1) & x_1^2(a_1) \\ 1 & x_2(a_2) & x_1^2(a_2) \\ 1 & x_2(a_3) & x_1^2(a_3) \end{vmatrix}}{\begin{vmatrix} 1 & x_1(a_1) & x_2(a_1) \\ 1 & x_1(a_2) & x_2(a_2) \\ 1 & x_1(a_3) & x_2(a_3) \end{vmatrix}}$$

that can be also written as *quotients* of diagonally symmetric polynomials:

$$d = - \frac{\begin{vmatrix} 3 & p_{01} & p_{20} \\ p_{10} & p_{11} & p_{30} \\ p_{01} & p_{02} & p_{21} \end{vmatrix}}{\begin{vmatrix} 3 & p_{10} & p_{01} \\ p_{10} & p_{20} & p_{11} \\ p_{01} & p_{11} & p_{02} \end{vmatrix}}.$$

## Gröbner bases with as many equations as unknowns

Choose a monomial order. Consider all systems

$$\begin{cases} F_1 = x_1^{d_1} + \text{smaller terms} \\ F_2 = x_2^{d_2} + \text{smaller terms} \\ \vdots \\ F_r = x_r^{d_r} + \text{smaller terms} \end{cases}$$

A formula from the Theory of multidimensional residues, due to Aizenberg and Kytmanov, provides the power sums as the coefficients in some series expansion:

$$\frac{x_1 \cdot x_2 \cdots x_r}{F_1 \cdot F_2 \cdots F_r} \cdot \left| \left( \frac{\partial F_i}{\partial x_j} \right) \right| = \sum_{\alpha \in \mathbb{N}^r} \frac{p_\alpha}{\mathbf{x}^\alpha} + \dots$$

that corresponds to *diagonally symmetric analogs of Newton's recursion formulas between coefficients and power sums.*

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